

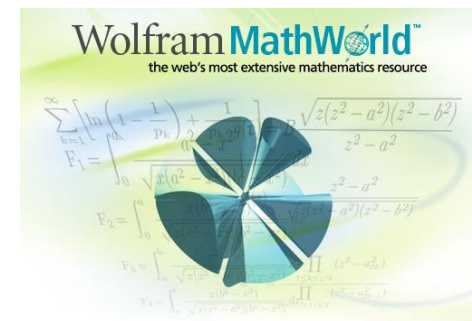
Summary

- ▶ Definition: Graph
- ▶ Related Definitions
- ▶ Applications
- ▶ Graph representation
- ▶ Graph visits

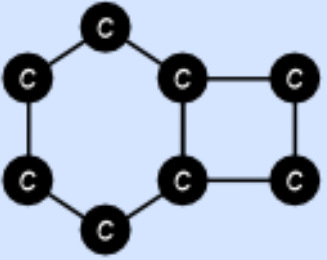
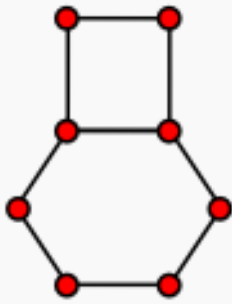
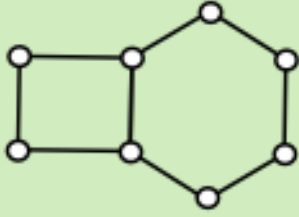







Definition: **Graph**

- ▶ A **graph** is a collection of **points** and **lines** connecting some (possibly empty) subset of them.
- ▶ The points of a graph are most commonly known as **graph vertices**, but may also be called “nodes” or simply “points.”
- ▶ The lines connecting the vertices of a graph are most commonly known as **graph edges**, but may also be called “arcs” or “lines.”

<http://mathworld.wolfram.com/>



What's in a name?

CHEMISTRY	SOCIAL NETWORKS	BIOLOGY	MATH
			<p>THEY LOOK THE SAME TO ME.</p> <p>LET'S CALL IT A GRAPH.</p>
<p>BENZOCYCLOBUTADIENE</p> <p> CARBON ATOMS</p> <p> σ-ELECTRON BONDS</p>	<p>spikedmath.com © 2011</p> <p> INDIVIDUALS</p> <p> FRIENDSHIPS</p>	<p>PPI (SUB)NETWORK OF A SIMPLE ORGANISM</p> <p> PROTEINS</p> <p> INTERACTIONS</p>	

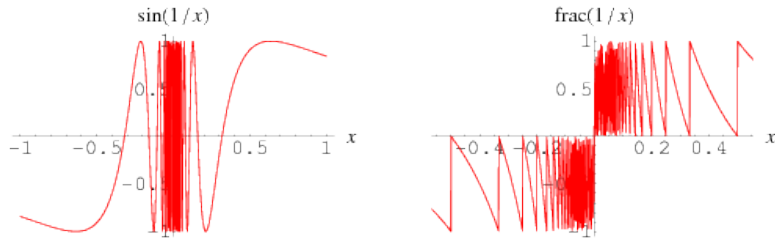
"MATHEMATICS IS THE ART OF GIVING THE SAME NAME TO DIFFERENT THINGS."

JULES HENRI POINCARÉ (1854-1912)

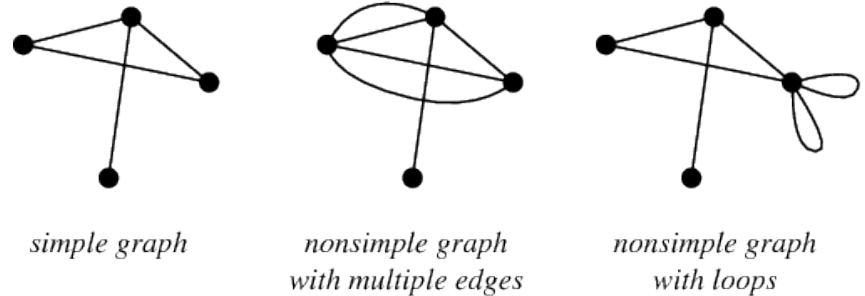
<http://spikedmath.com/382.html>

Big warning: Graph \neq Graph \neq Graph

Graph (plot)
(italiano: grafico)

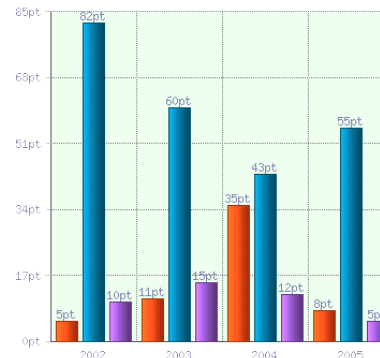


Graph (maths)
(italiano: grafo)



\neq

Graph (chart)
(italiano: grafico)



History

- ▶ The study of graphs is known as **graph theory**, and was first systematically investigated by D. König in the 1930s
- ▶ Euler's proof about the *walk across all seven bridges of Königsberg* (1736), now known as the *Königsberg bridge problem*, is a famous precursor to graph theory.
- ▶ In fact, the study of various sorts of paths in graphs has many applications in real-world problems.

Königsberg Bridge Problem

- ▶ Can the 7 bridges of the city of Königsberg over the river Pregel all be traversed in a single trip without doubling back, with the additional requirement that the trip ends in the same place it began?

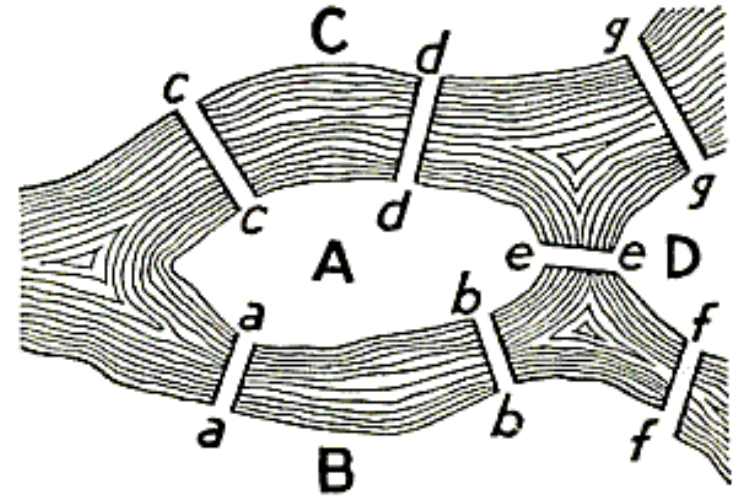
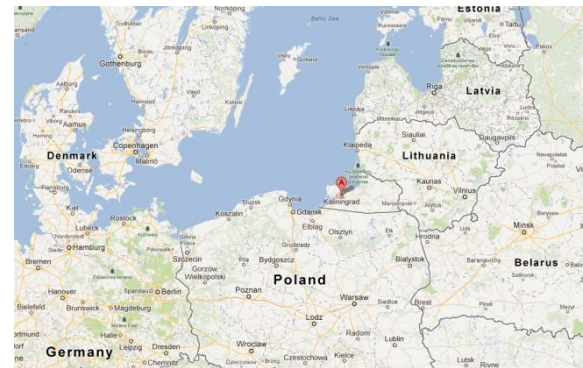


FIGURE 98. *Geographic Map:
The Königsberg Bridges.*



Today: Kaliningrad, Russia

Königsberg Bridge Problem

- ▶ Can the 7 bridges of the city of Königsberg over the river Pregel all be traversed in a single trip without crossing any bridge twice, and returning to the starting point?

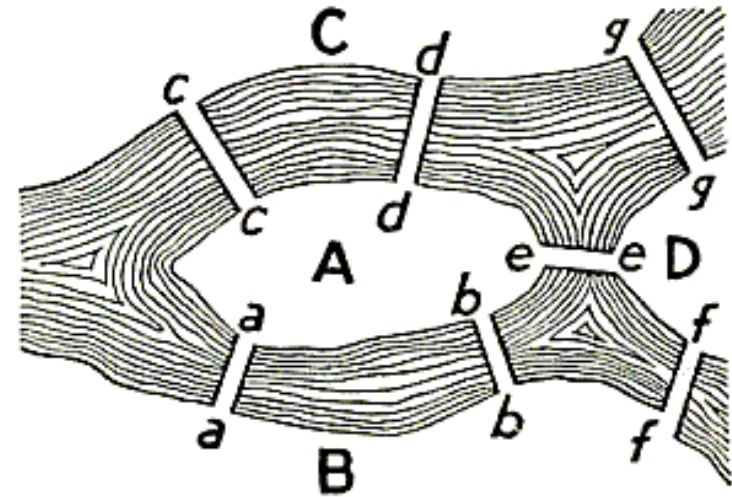
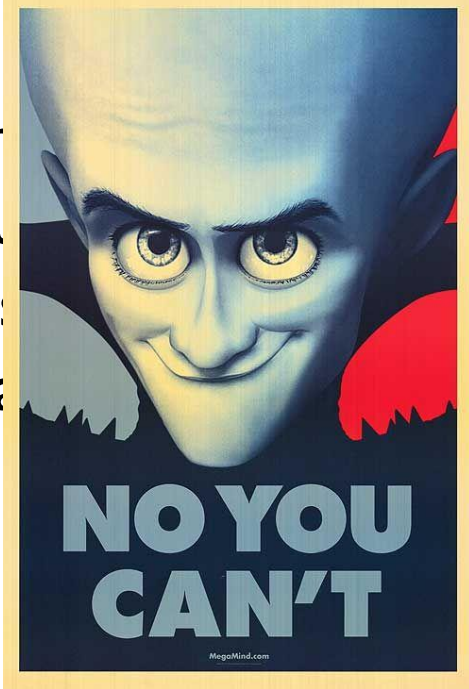
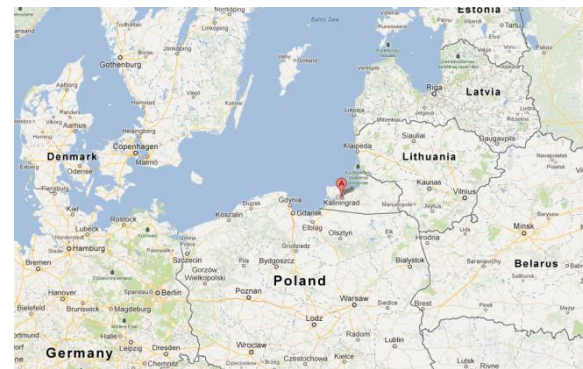
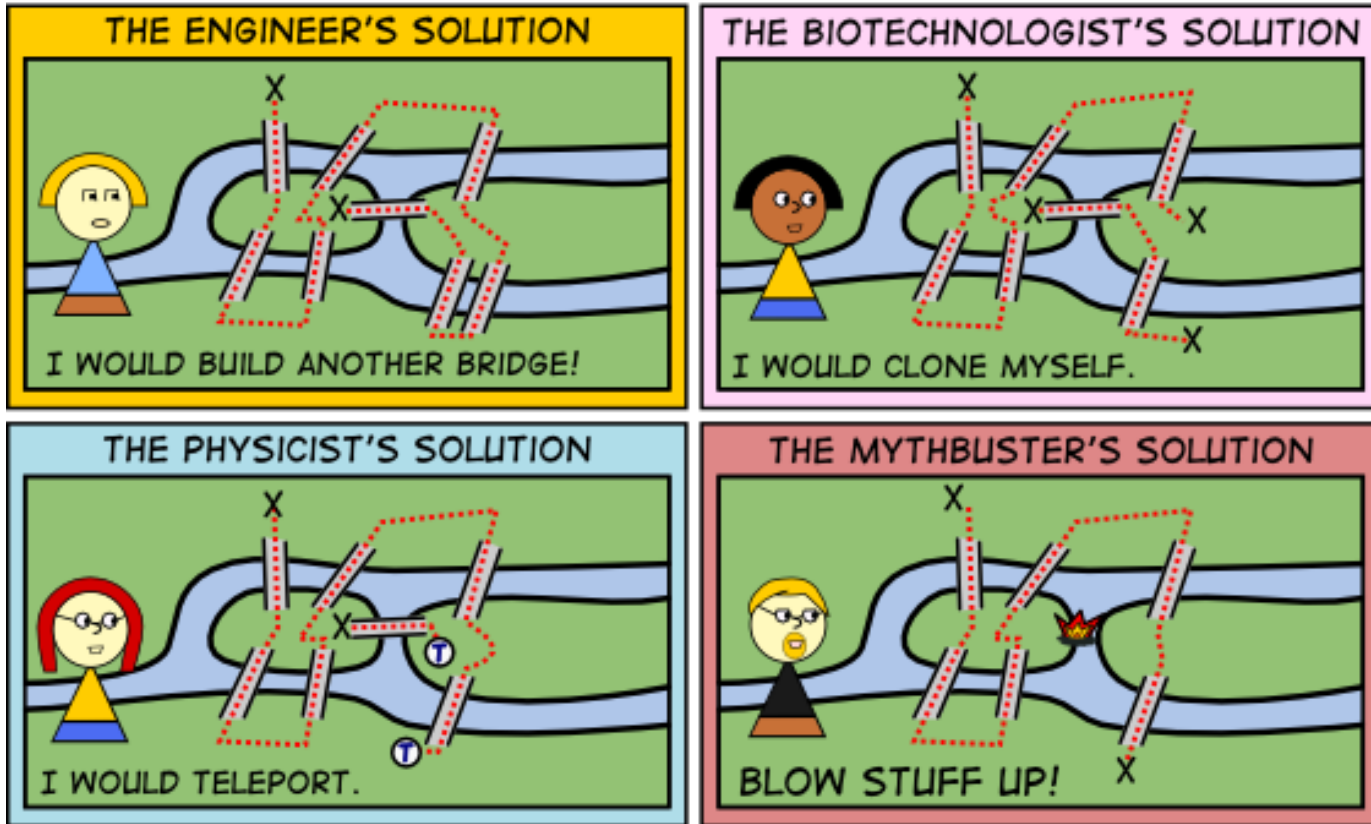


FIGURE 98. *Geographic Map:
The Königsberg Bridges.*



Today: Kaliningrad, Russia

Unless...

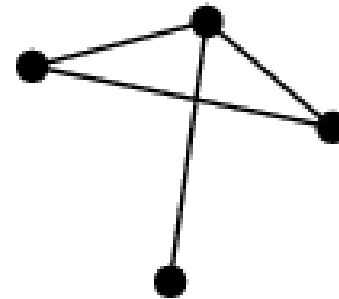


<http://spikedmath.com/541.html>

Types of graphs: edge cardinality

- ▶ **Simple graph:**

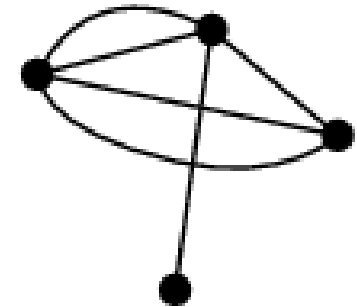
- ▶ At most one edge (i.e., either one edge or no edges) may connect any two vertices



simple graph

- ▶ **Multigraph:**

- ▶ Multiple edges are allowed between vertices



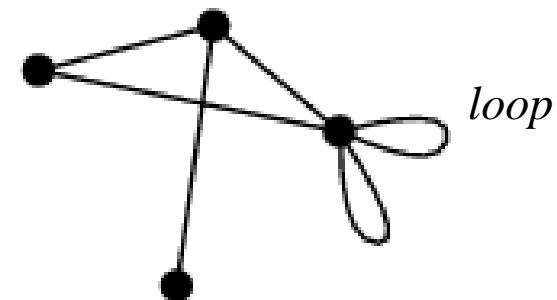
multigraph

- ▶ **Loops:**

- ▶ Edge between a vertex and itself

- ▶ **Pseudograph:**

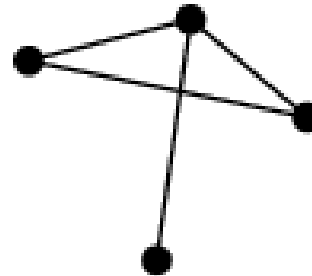
- ▶ Multigraph with loops



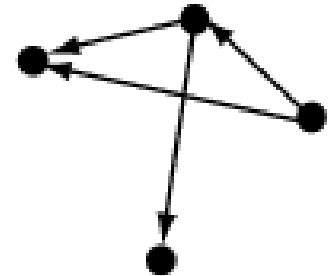
pseudograph

Types of graphs: edge direction

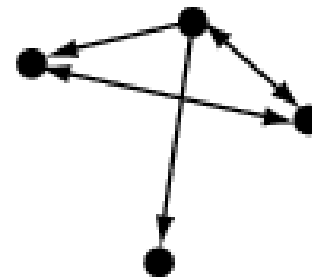
- ▶ **Undirected**
- ▶ **Oriented**
 - ▶ Edges have **one** direction (indicated by arrow)
- ▶ **Directed**
 - ▶ Edges may have **one or two** directions
- ▶ **Network**
 - ▶ Oriented graph with weighted edges



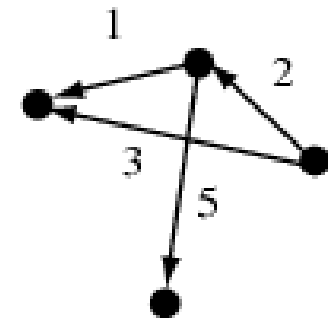
undirected graph



oriented graph



directed graph



network

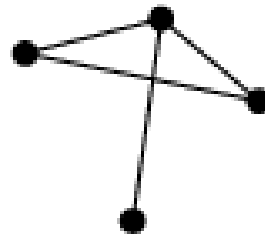
Types of graphs: labeling

▶ Labels

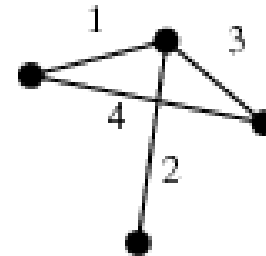
- ▶ None
- ▶ On Vertices
- ▶ On Edges

▶ Groups (=colors)

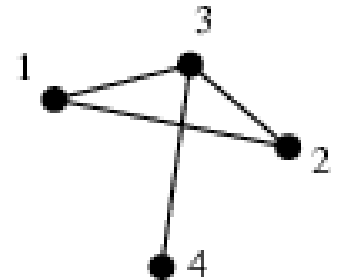
- ▶ Of Vertices
 - ▶ no edge connects two identically colored vertices
- ▶ Of Edges
 - ▶ adjacent edges must receive different colors
- ▶ Of both



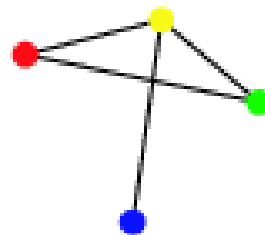
unlabeled graph



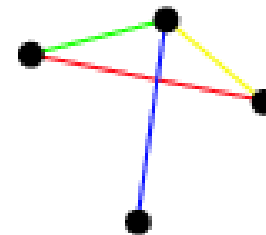
edge-labeled graph



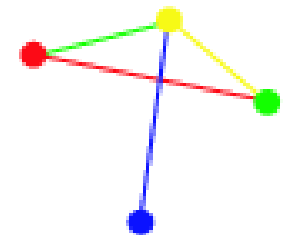
vertex-labeled graph



vertex-colored graph



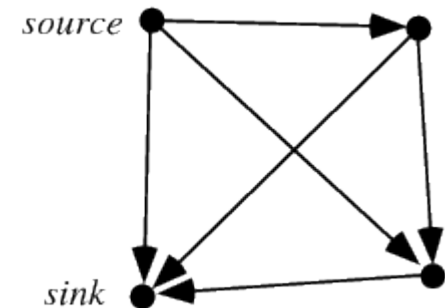
edge-colored graph



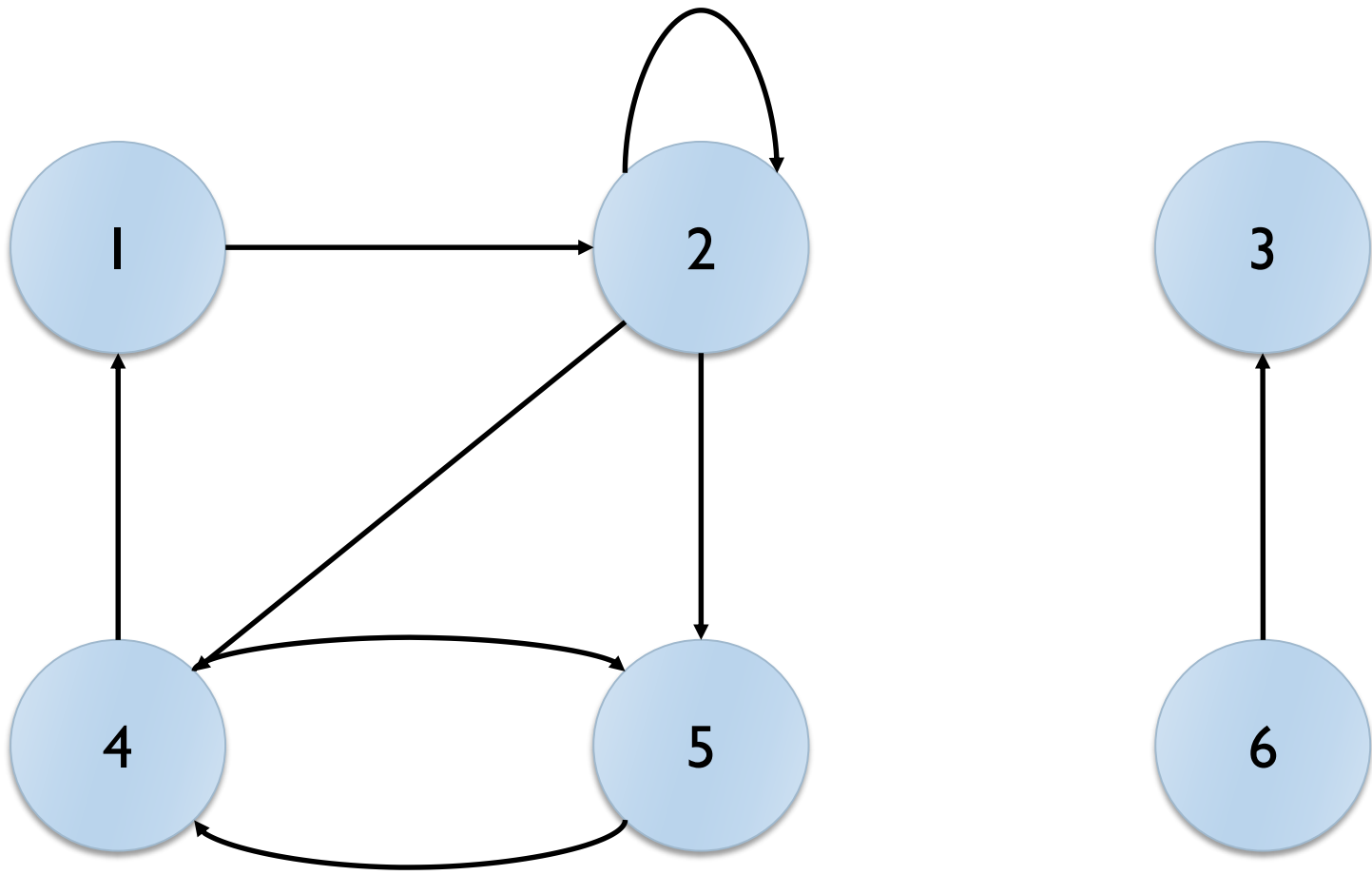
vertex- and edge-colored graph

Directed and Oriented graphs

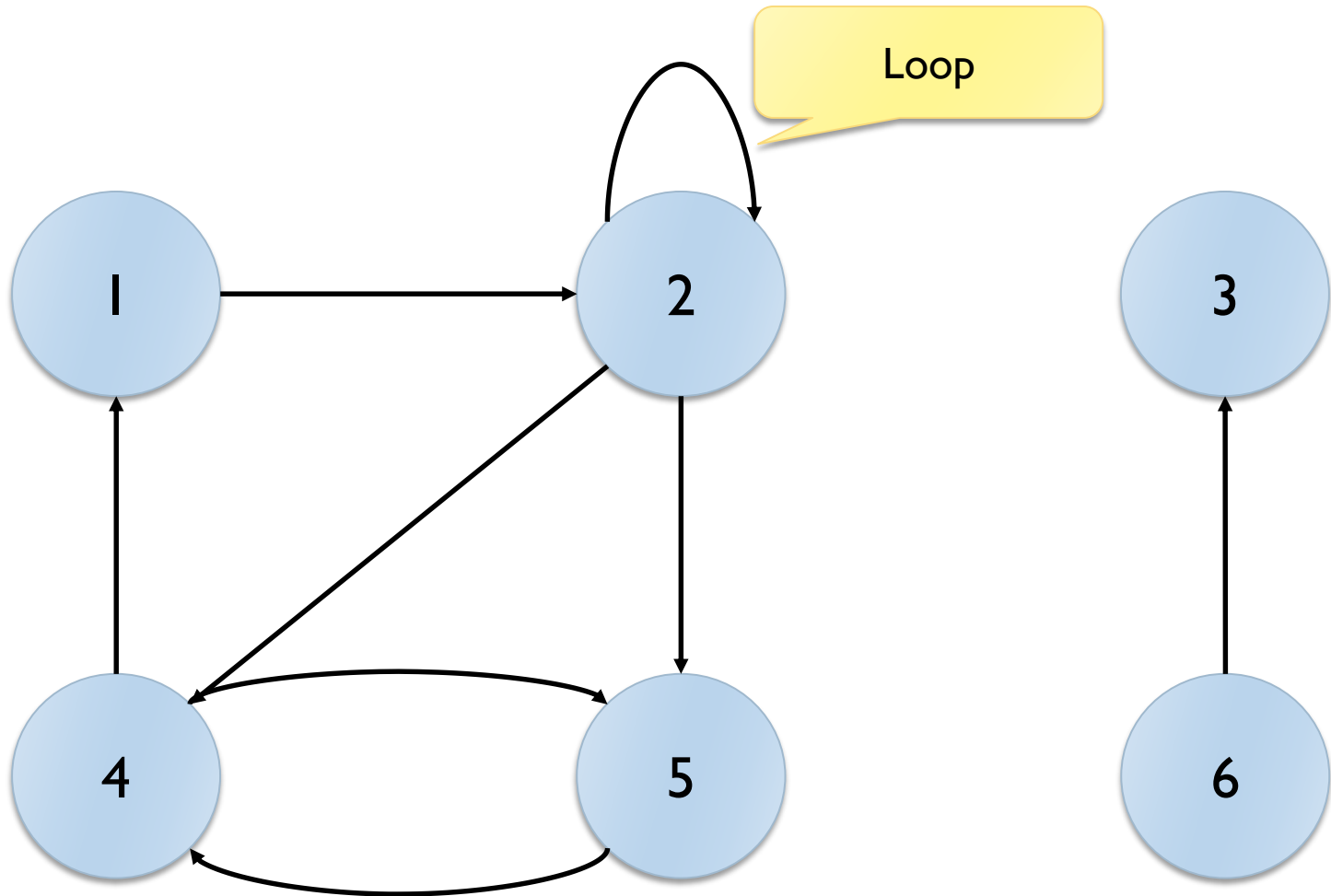
- ▶ A Directed Graph (*di-graph*) G is a pair (V,E) , where
 - ▶ V is a (finite) set of *vertices*
 - ▶ E is a (finite) set of *edges*, that identify a binary relationship over V
 - ▶ $E \subseteq V \times V$



Example



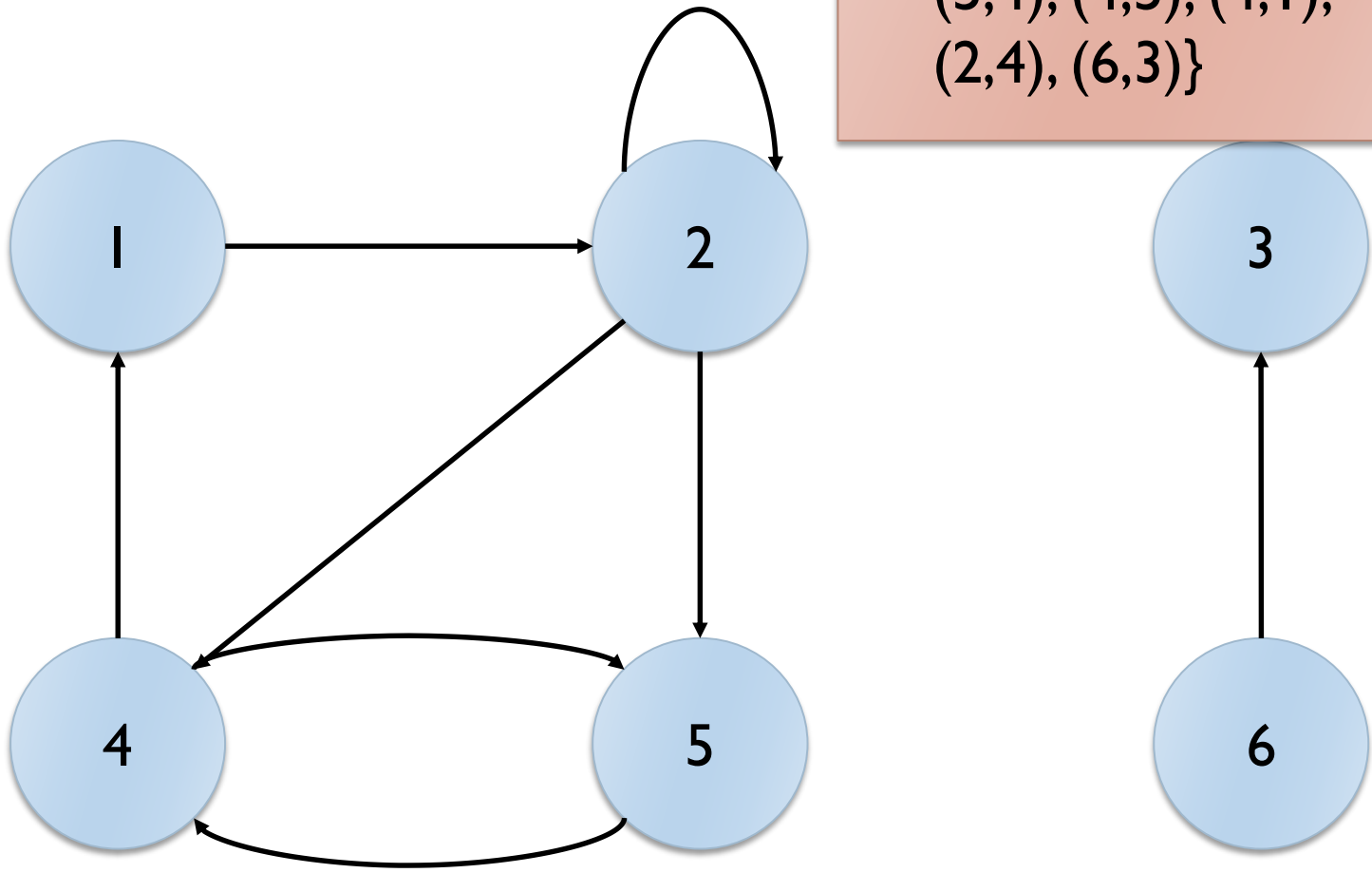
Example



Example

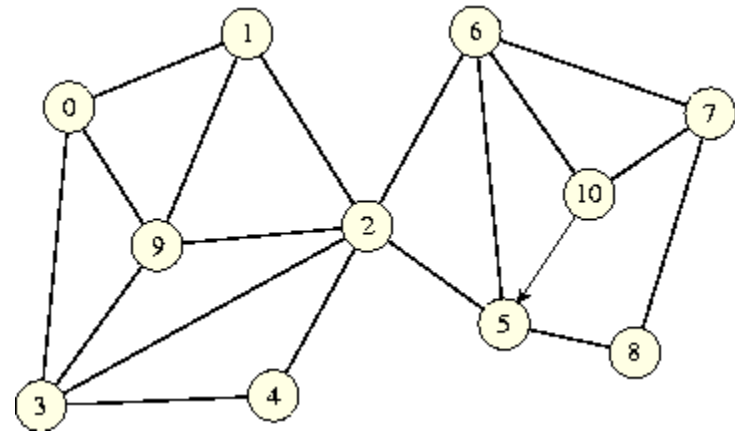
$$V = \{1, 2, 3, 4, 5, 6\}$$

$$E = \{(1, 2), (2, 2), (2, 5), (5, 4), (4, 5), (4, 1), (2, 4), (6, 3)\}$$



Undirected graph

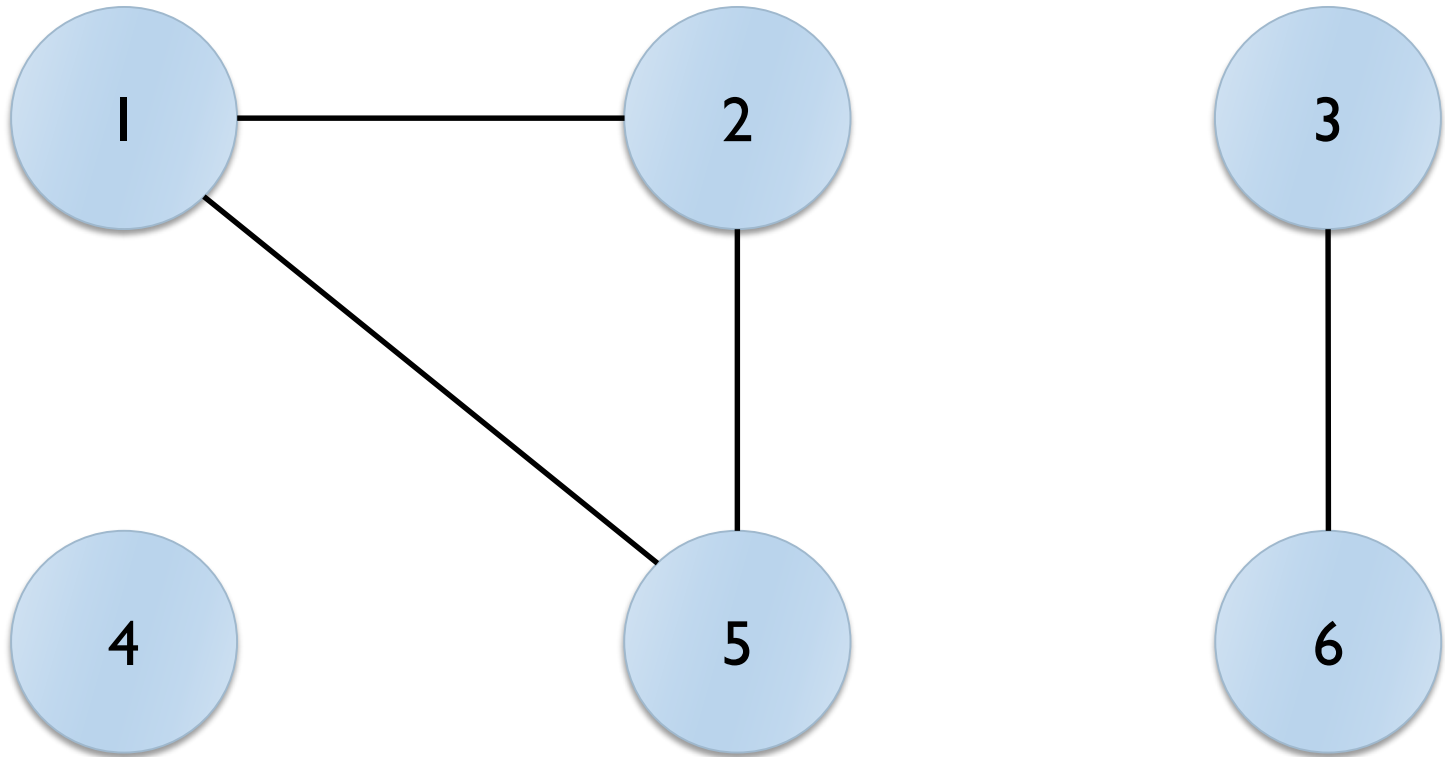
- ▶ Ad **Undirected** Graph is still represented as a couple $G=(V,E)$, but the set E is made of **non-ordered pairs** of vertices



Example

$V = \{1, 2, 3, 4, 5, 6\}$

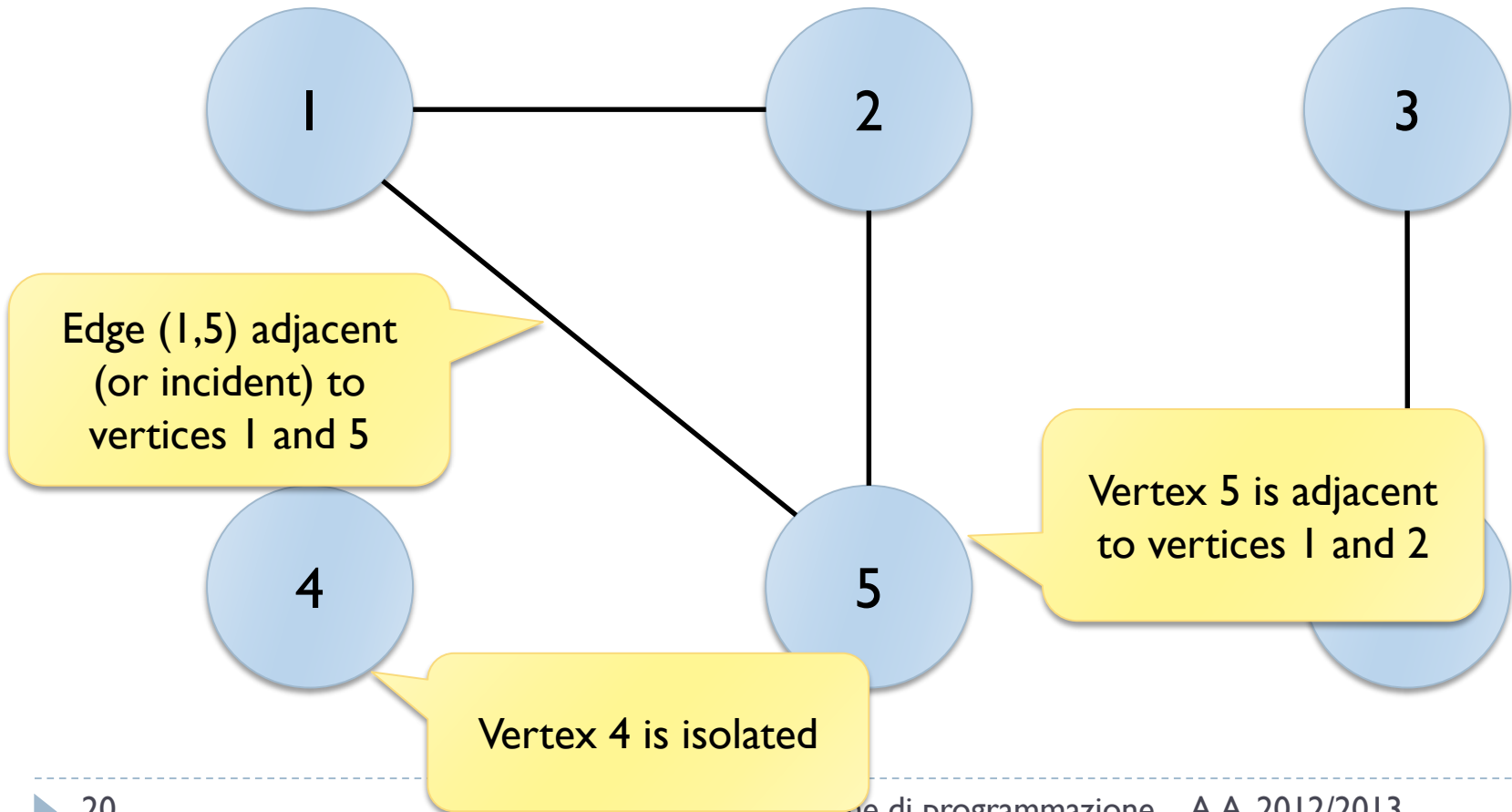
$E = \{(1, 2), (2, 5), (5, 1), (6, 3)\}$



Example

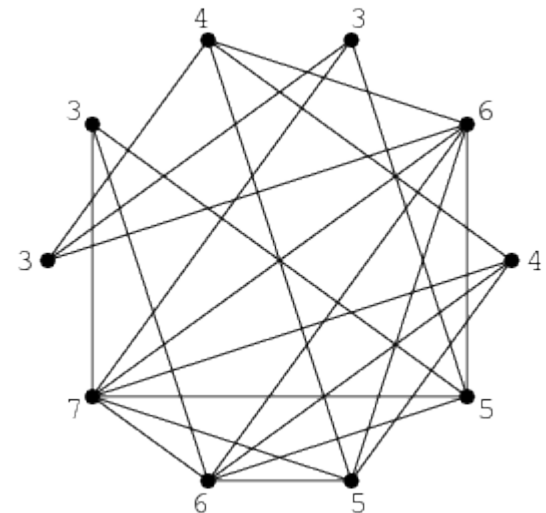
$V = \{1, 2, 3, 4, 5, 6\}$

$E = \{(1, 2), (2, 5), (5, 1), (6, 3)\}$

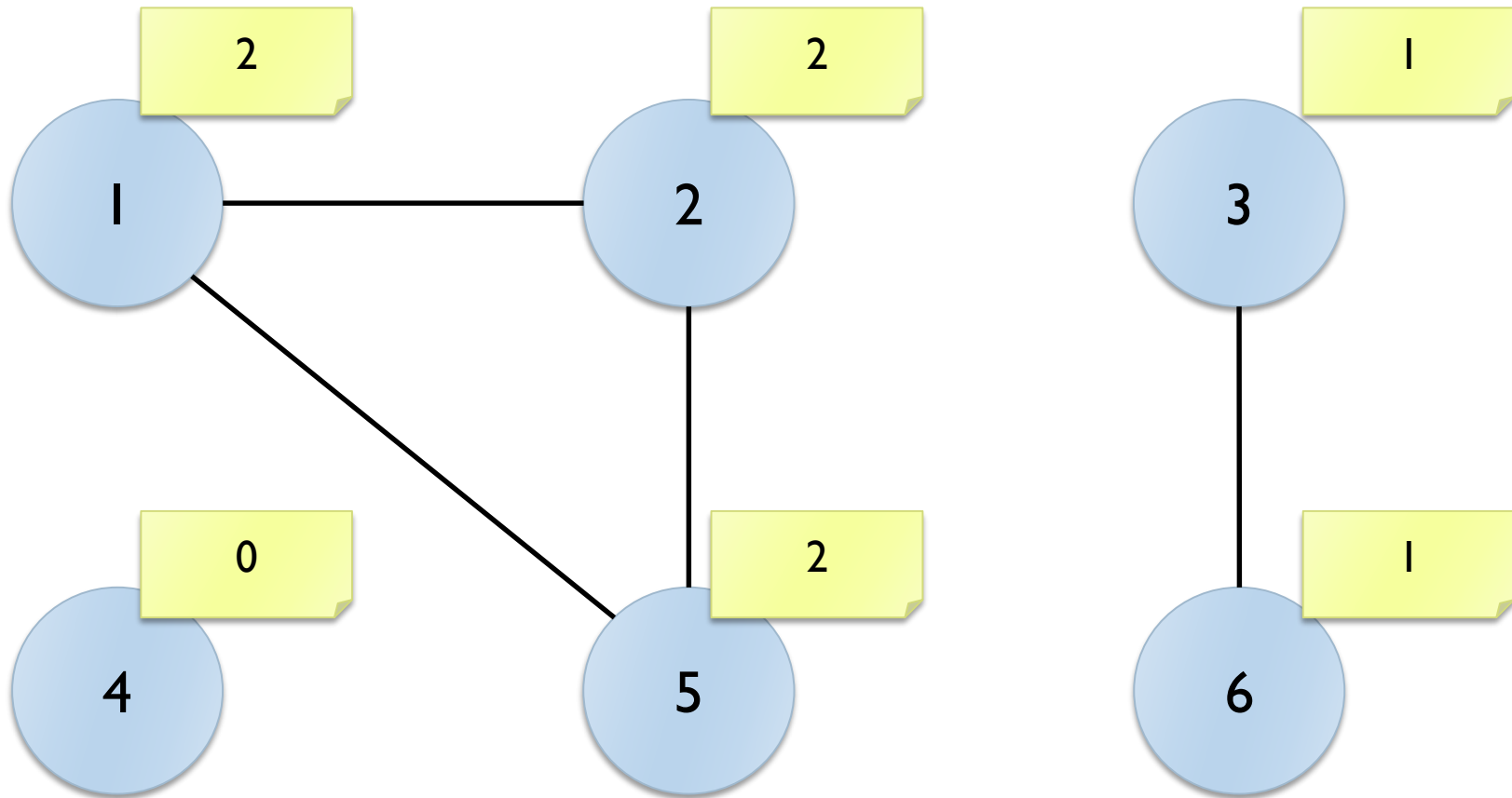


Degree

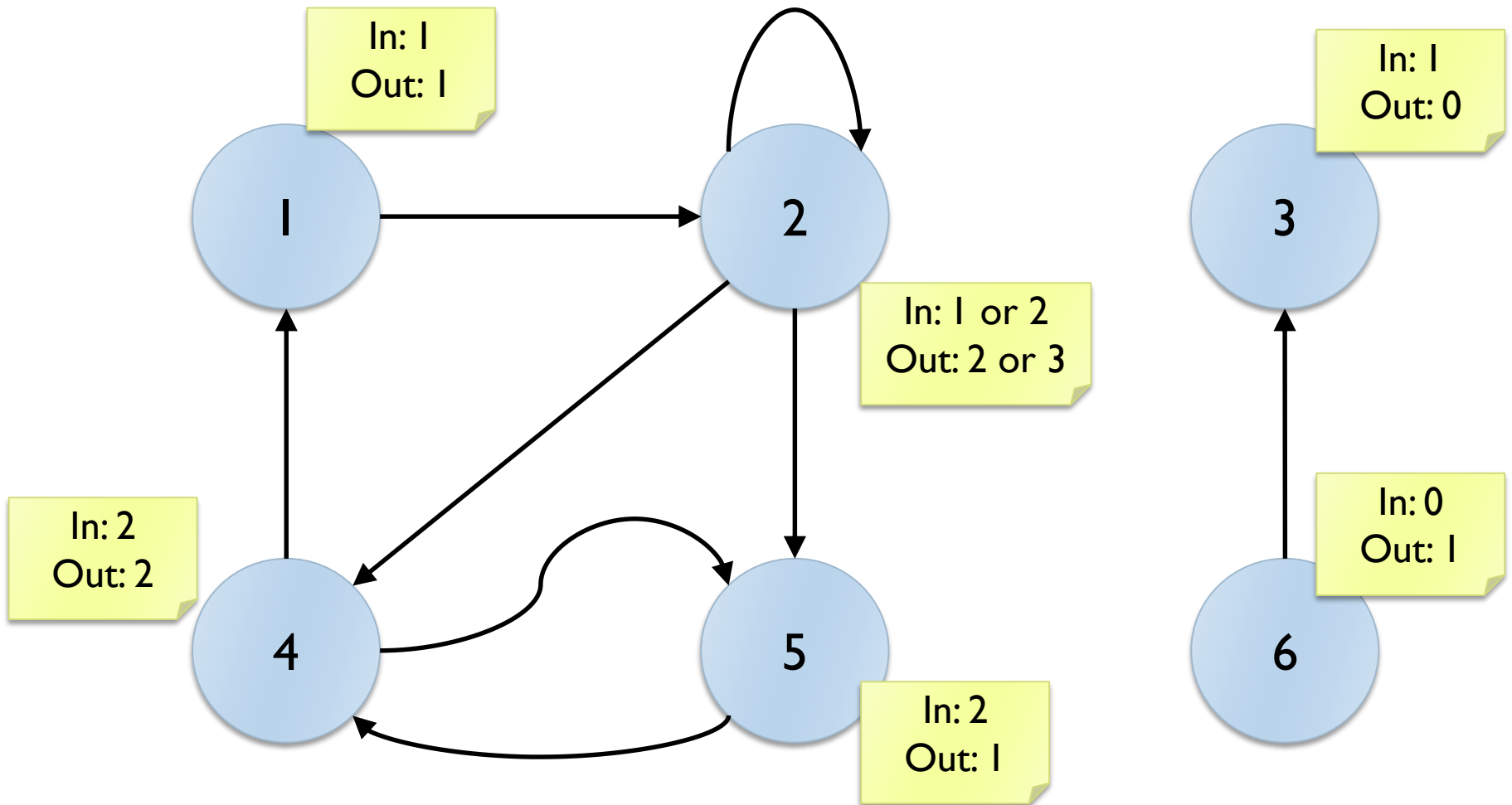
- ▶ In an *undirected* graph,
 - ▶ the **degree** of a vertex is the number of incident edges
- ▶ In a *directed* graph
 - ▶ The **in-degree** is the number of incoming edges
 - ▶ The **out-degree** is the number of departing edges
 - ▶ The **degree** is the sum of in-degree and out-degree
- ▶ A vertex with degree 0 is **isolated**



Degree



Degree

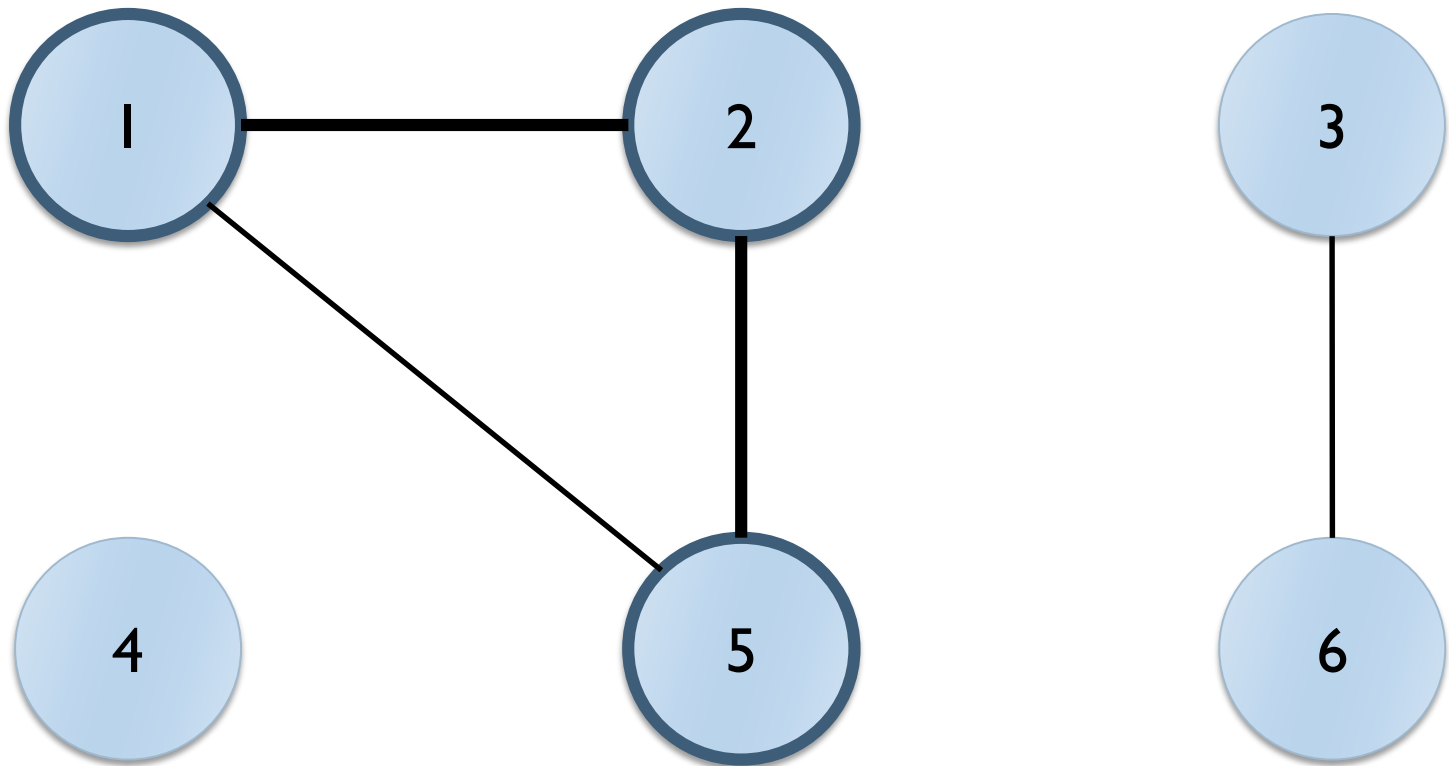


Paths

- ▶ A **path** on a graph $G=(V,E)$ also called a trail, is a sequence $\{v_1, v_2, \dots, v_n\}$ such that:
 - ▶ v_1, \dots, v_n are vertices: $v_i \in V$
 - ▶ $(v_1, v_2), (v_2, v_3), \dots, (v_{n-1}, v_n)$ are graph edges: $(v_{i-1}, v_i) \in E$
 - ▶ v_i are distinct (for “simple” paths).
- ▶ The **length** of a path is the number of edges $(n-1)$
- ▶ If there exist a path between v_A and v_B we say that v_B is **reachable** from v_A

Example

Path = { 1, 2, 5 }
Length = 2

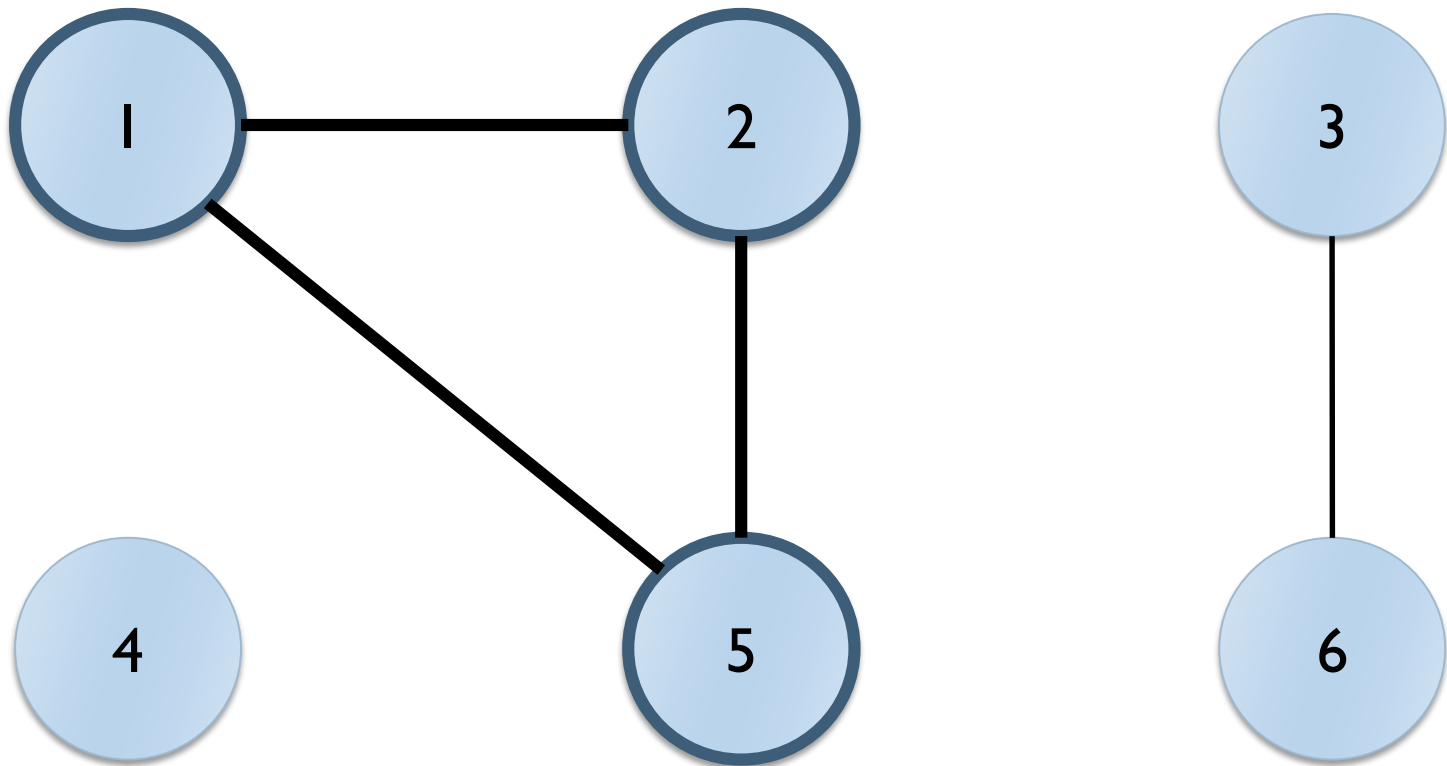


Cycles

- ▶ A cycle is a path where $v_1 = v_n$
- ▶ A graph with no cycles is said acyclic

Example

Path = { 1, 2, 5, 1 }
Length = 3



Reachability (Undirected)

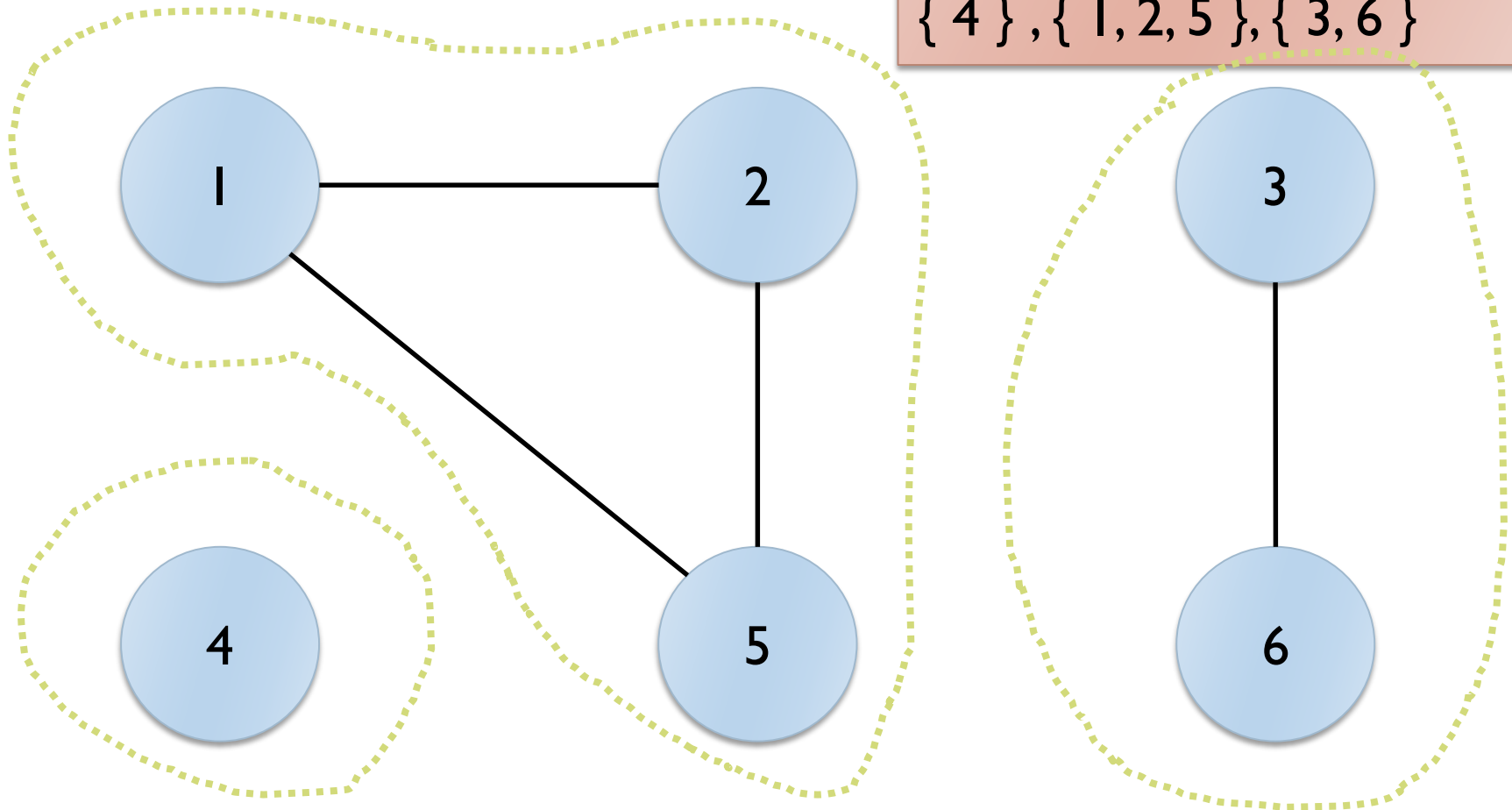
- ▶ An undirected graph is **connected** if, for every couple of vertices, there is a path connecting them
- ▶ The connected sub-graph of maximum size are called **connected components**
- ▶ A connected graph has exactly one connected component

Connected components

The graph is **not** connected.

Connected components =
3

$\{ 4 \}, \{ 1, 2, 5 \}, \{ 3, 6 \}$

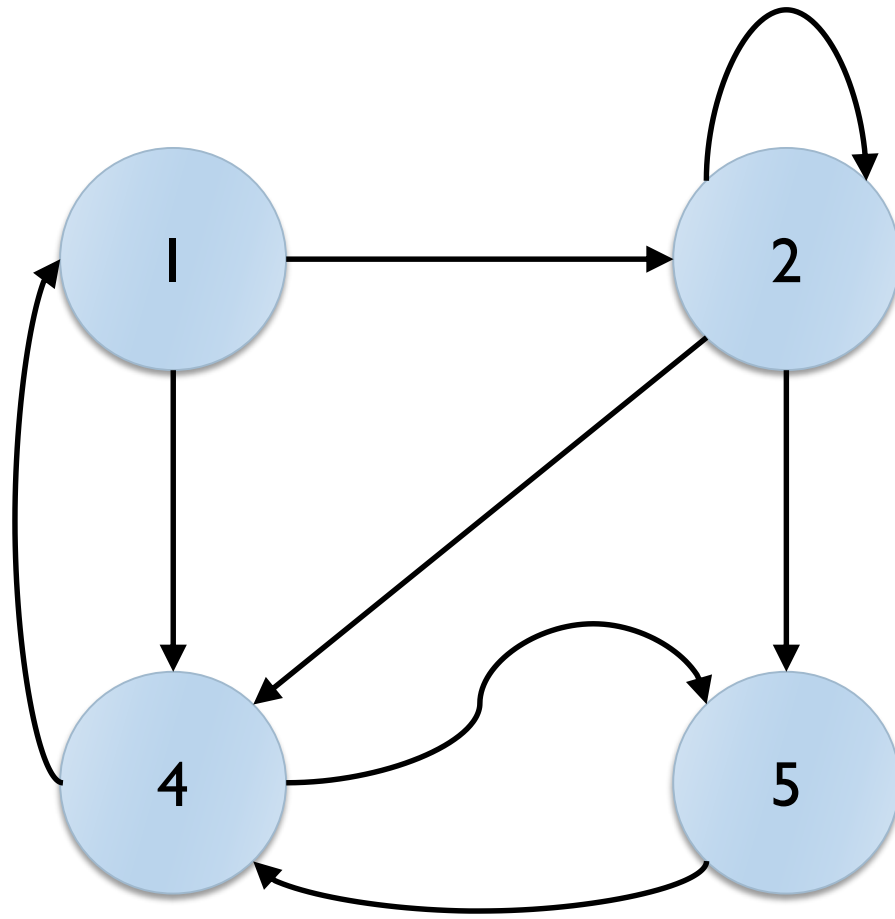


Reachability (Directed)

- ▶ A directed graph is **strongly connected** if, for every ordered pair of vertices (v, v') , there exists at least one path connecting v to v'

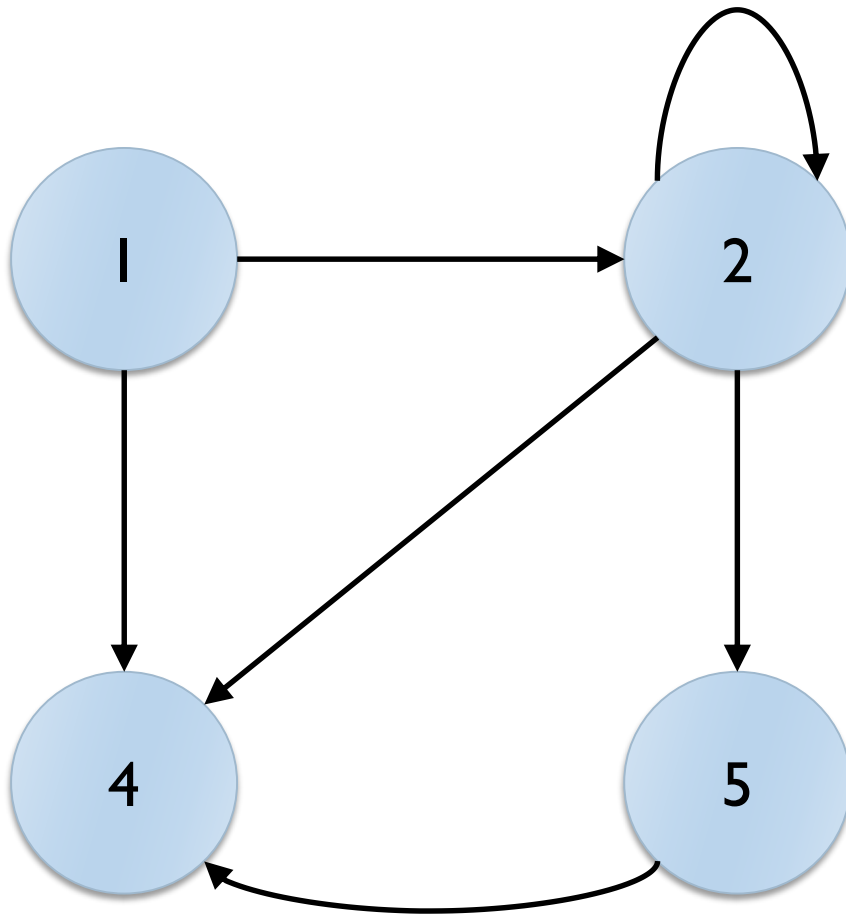
Example

The graph is **strongly connected**



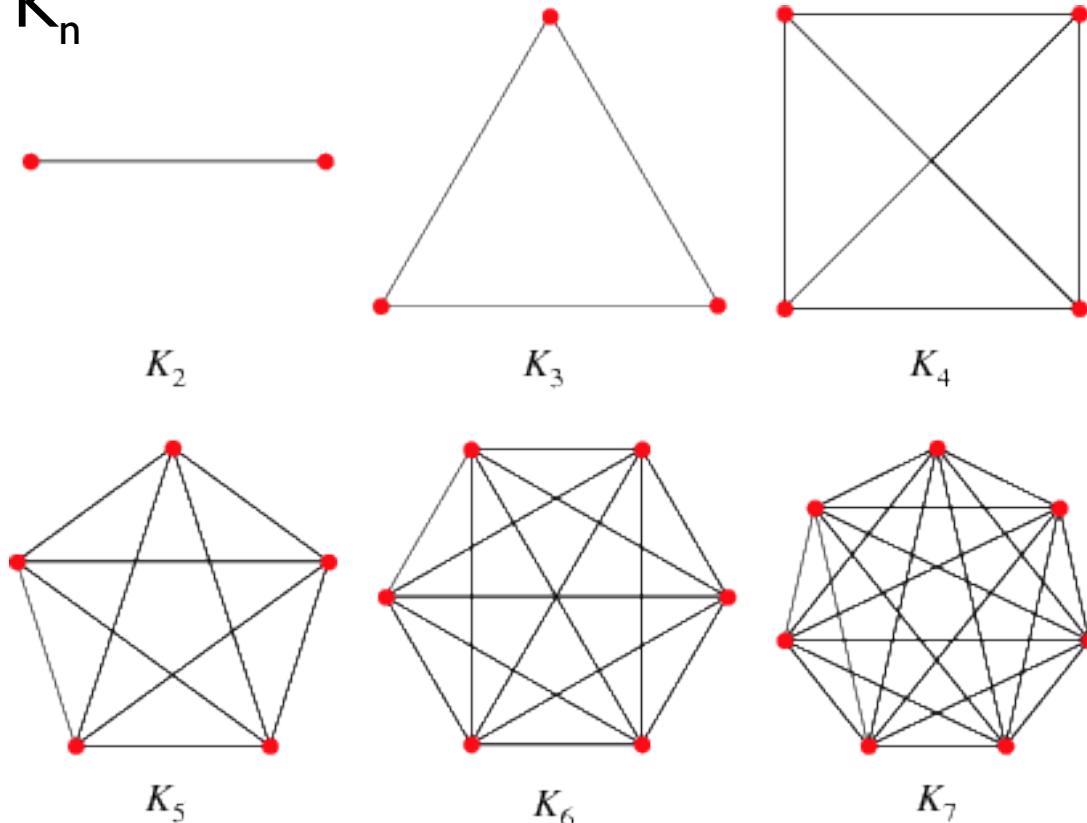
Example

The graph is **not** strongly connected



Complete graph

- ▶ A graph is complete if, for every pair of vertices, there is an edge connecting them (they are adjacent)
- ▶ Symbol: K_n



Complete graph: edges

- ▶ In a **complete** graph with n vertices, the number of **edges** is
 - ▶ $n(n-1)$, if the graph is directed
 - ▶ $n(n-1)/2$, if the graph is undirected
 - ▶ If self-loops are allowed, then
 - ▶ n^2 for directed graphs
 - ▶ $n(n-1)$ for undirected graphs

Density

- ▶ The density of a graph $G=(V,E)$ is the ratio of the number of edges to the total number of edges

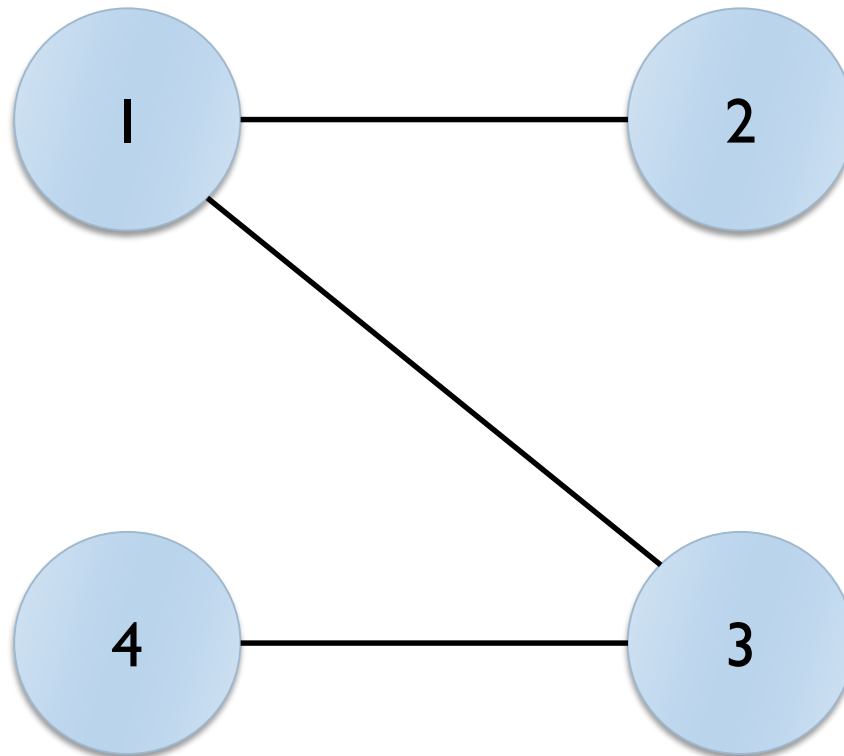
$$d = \frac{|E(G)|}{|E(K_{|V(G)|})|}$$

Esempio

Density = 0.5

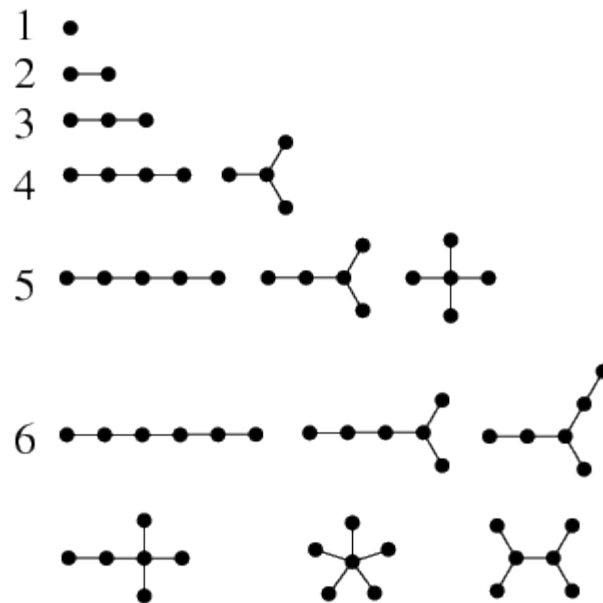
Existing: 3 edges

Total: 6 possible edges



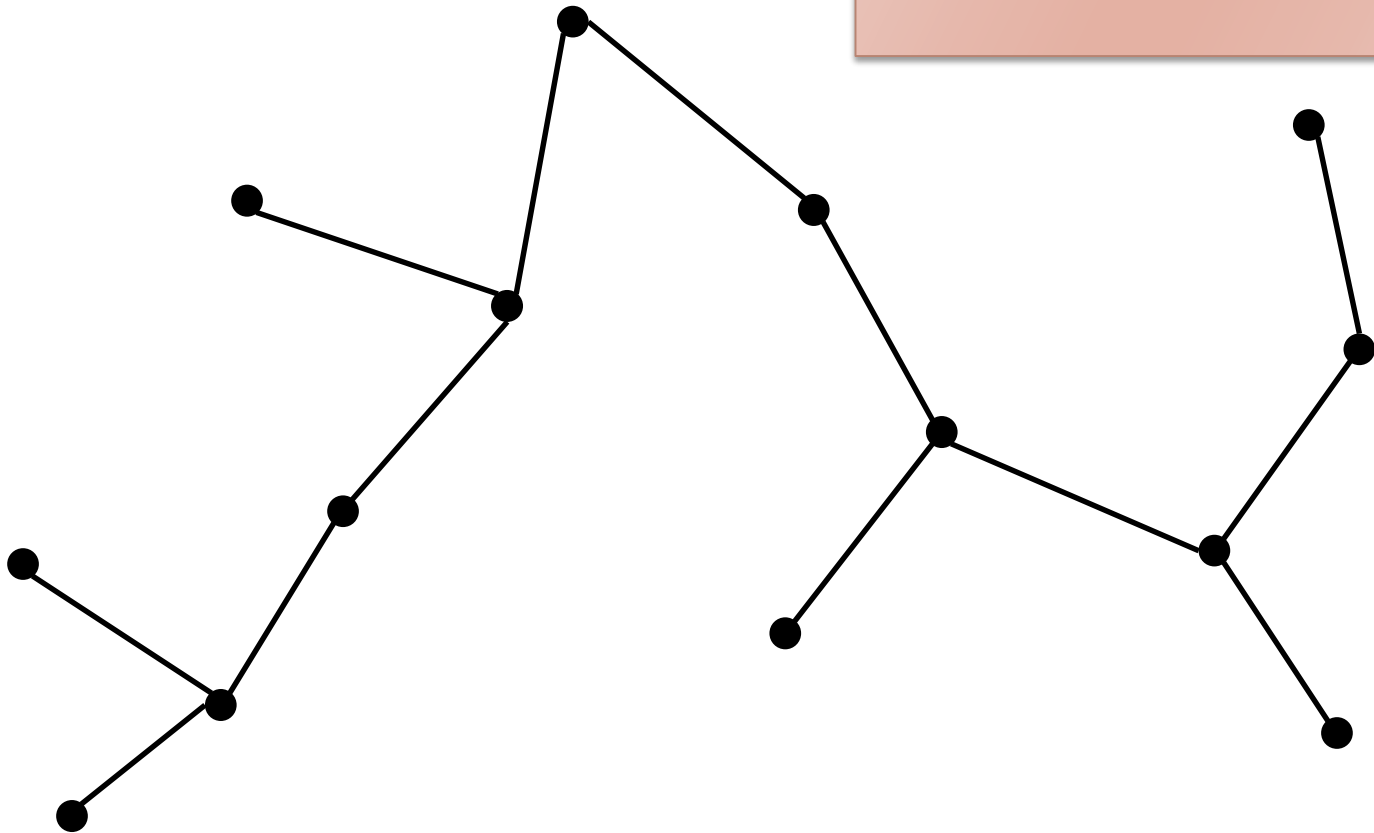
Trees and Forests

- ▶ An undirected acyclic graph is called **forest**
- ▶ An undirected acyclic connected graph is called **tree**



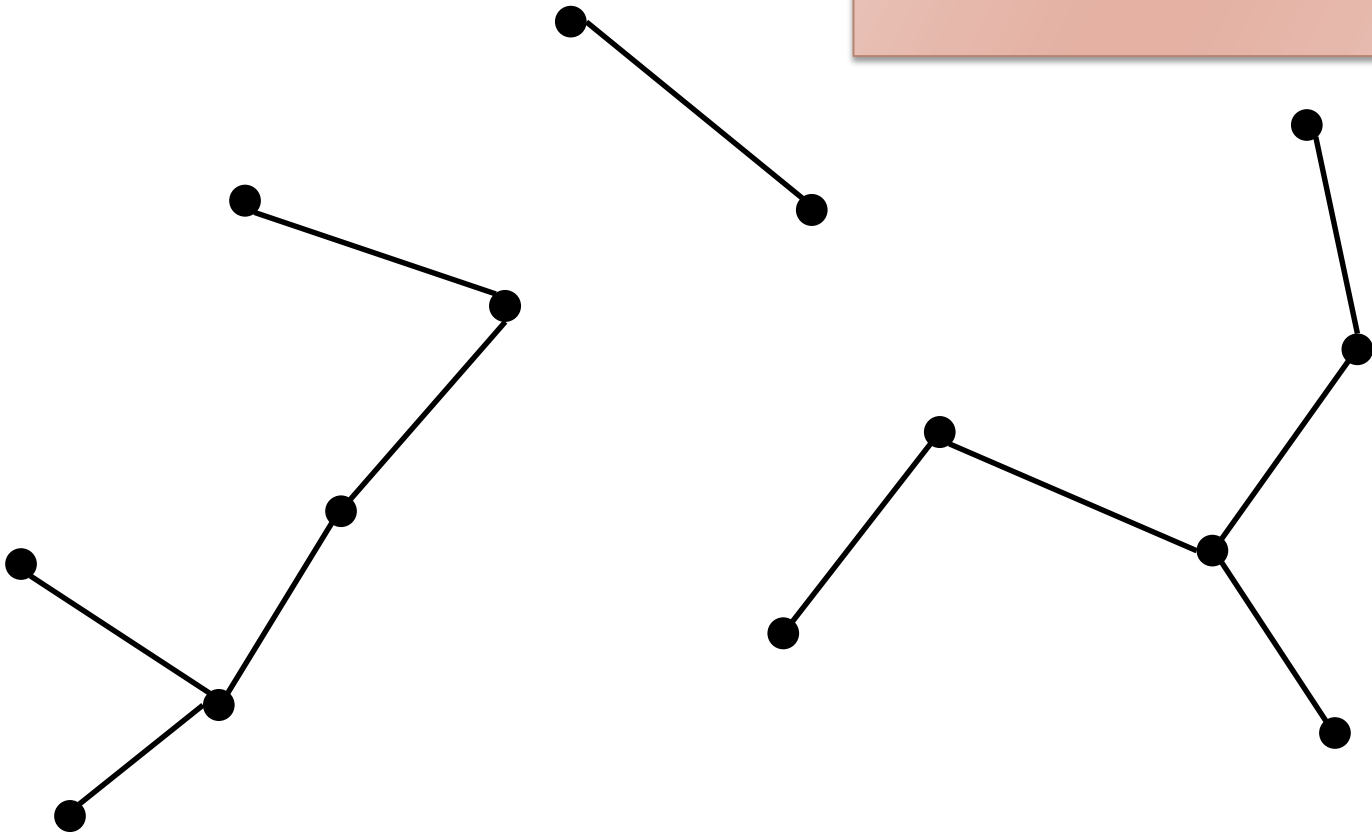
Example

Tree



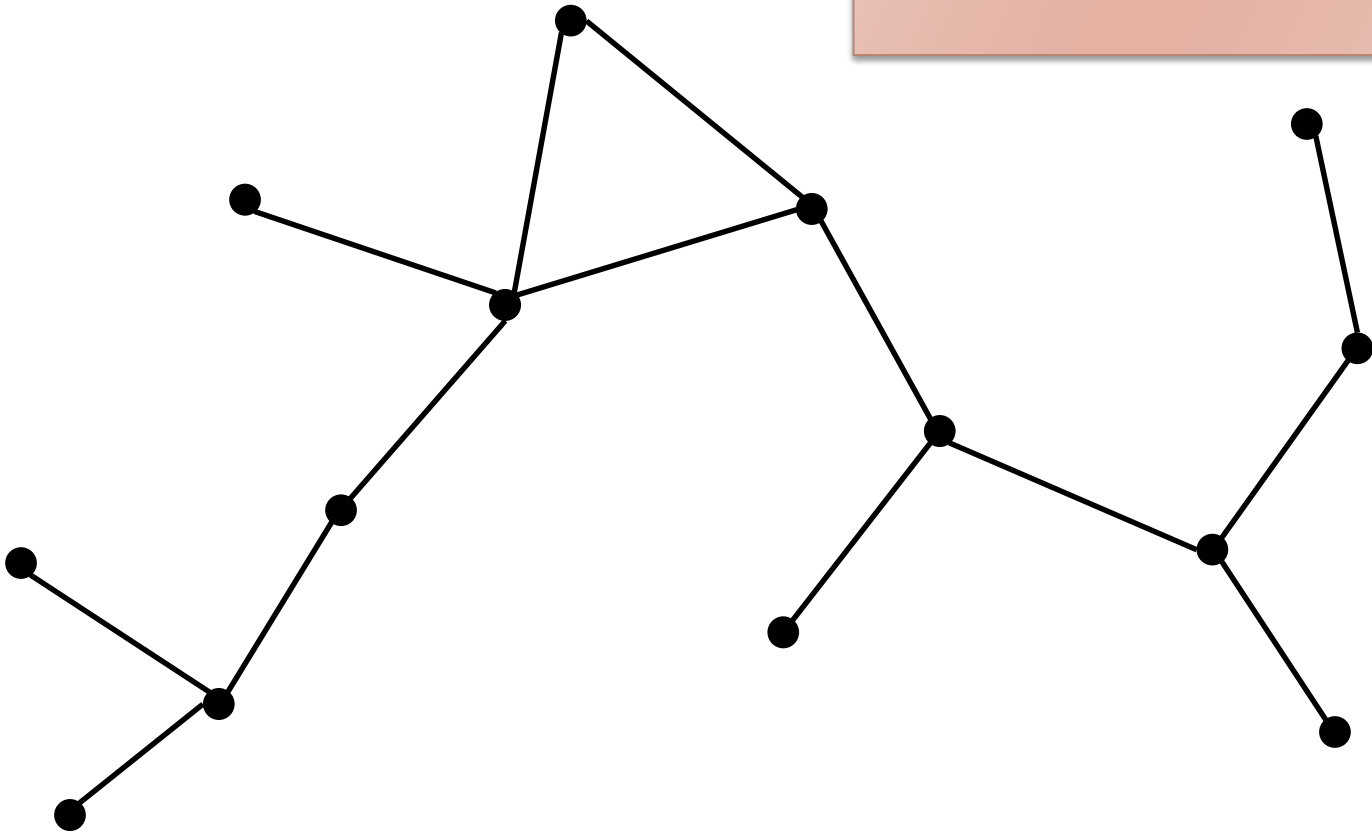
Example

Forest



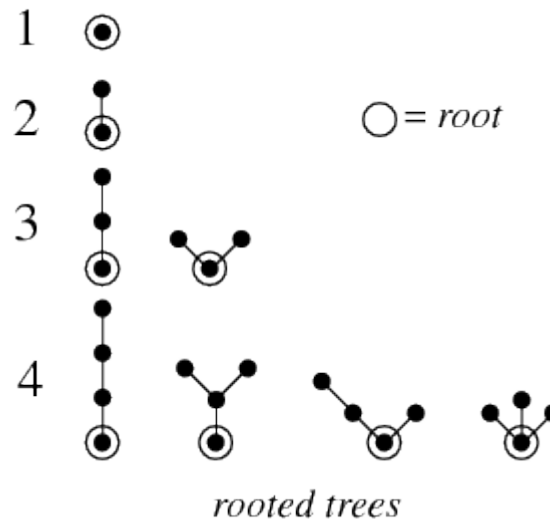
Example

This is not a tree nor a forest
(it contains a cycle)



Rooted trees

- ▶ In a tree, a special node may be singled out
- ▶ This node is called the “**root**” of the tree
- ▶ Any node of a tree can be the root

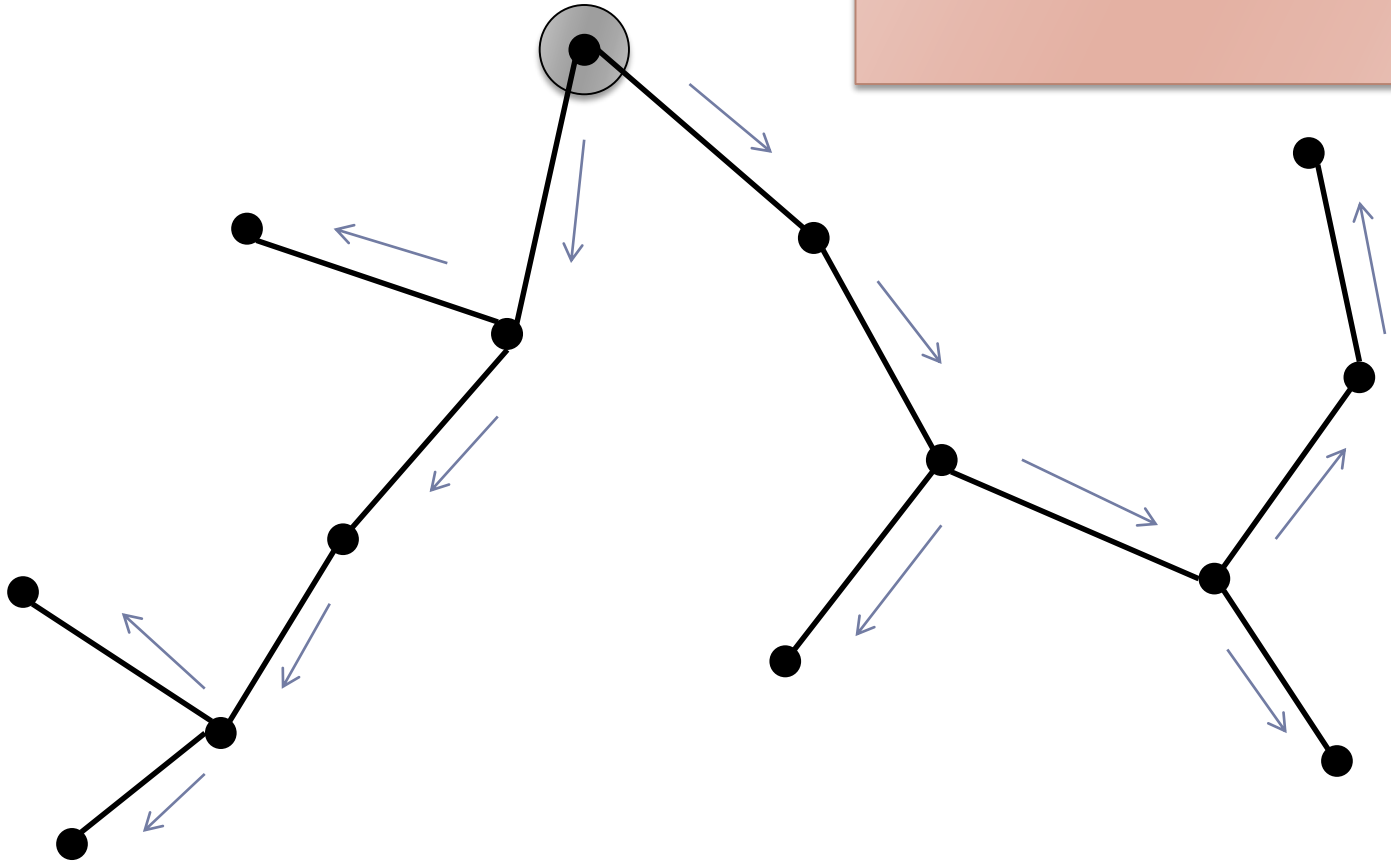


Tree (implicit) ordering

- ▶ The root node of a tree **induces an ordering** of the nodes
- ▶ The root is the “ancestor” of all other nodes/vertices
 - ▶ “children” are “away from the root”
 - ▶ “parents” are “towards the root”
- ▶ The root is the only node without parents
- ▶ All other nodes have exactly one parent
- ▶ The furthestmost (children-of-children-of-children...) nodes are “leaves”

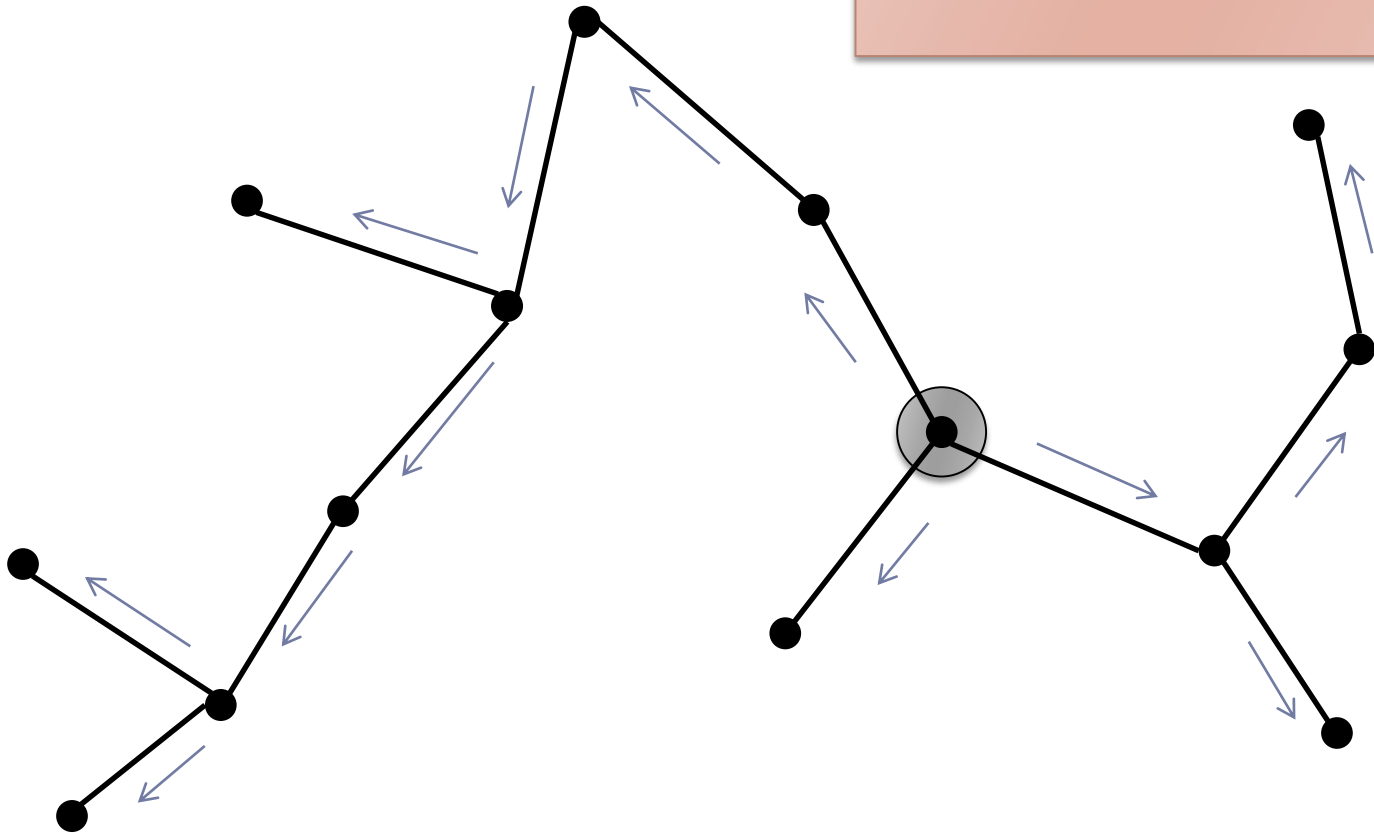
Example

Rooted Tree



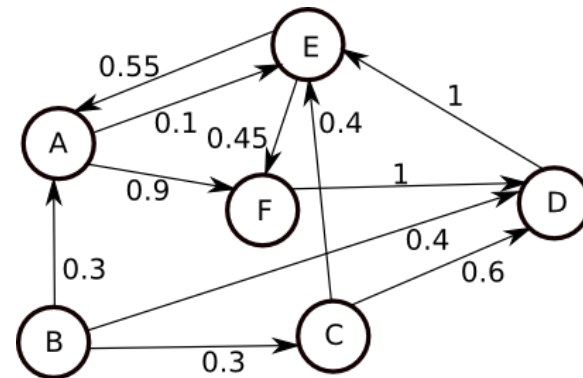
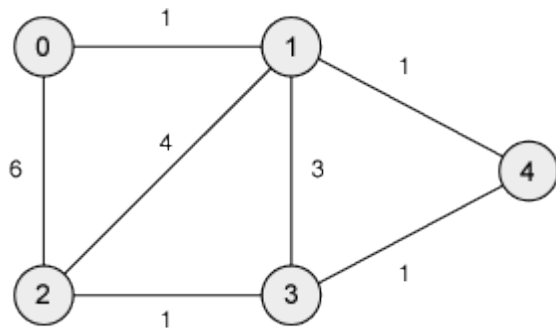
Example

Rooted Tree



Weighted graphs

- ▶ A weighted graph is a graph in which each branch (edge) is given a numerical weight.
- ▶ A weighted graph is therefore a special type of labeled graph in which the labels are numbers (which are usually taken to be positive).



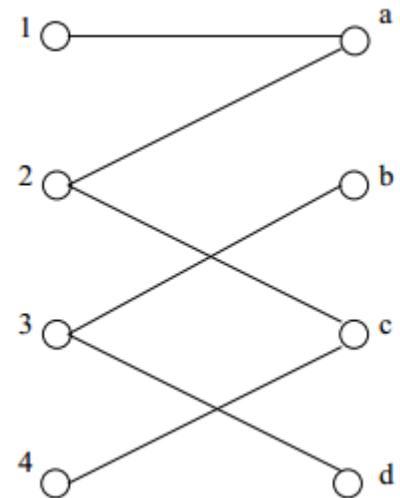
Graph applications

▶ Graphs are everywhere

- ▶ Facebook friends (and posts, and 'likes')
- ▶ Football tournaments (complete subgraphs + binary tree)
- ▶ Google search index (V =page, E =link, w =pagerank)
- ▶ Web analytics (site structure, visitor paths)
- ▶ Car navigation (GPS)
- ▶ Market Matching

Market matching

- ▶ $H = \text{Houses } (1, 2, 3, 4)$
- ▶ $B = \text{Buyers } (a, b, c, d)$
- ▶ $V = H \cup B$
- ▶ Edges: $(h, b) \in E$ if b would like to buy h
- ▶ Problem: can all houses be sold and all buyers be satisfied?
- ▶ Variant: if the graph is weighted with a purchase offer, what is the most convenient solution?
- ▶ Variant: consider a 'penalty' for unsold items



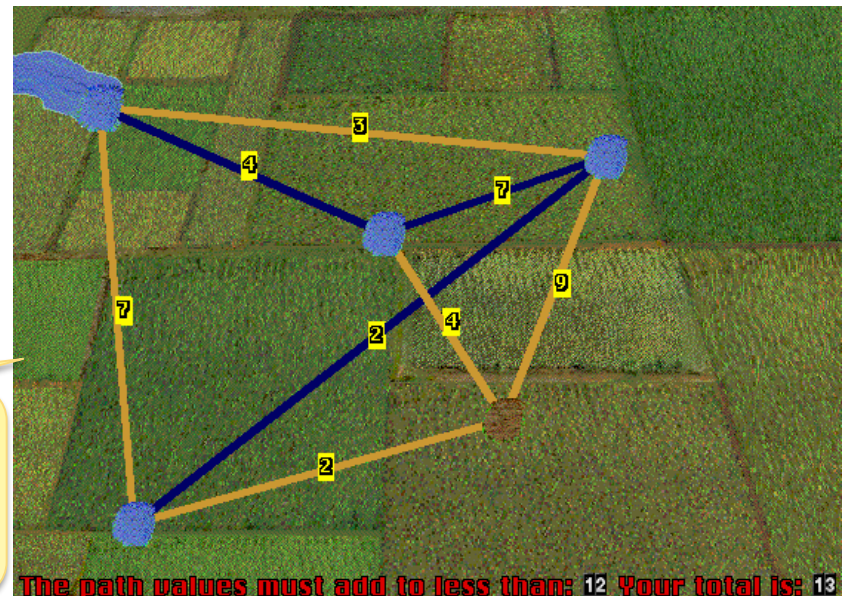
This graph is called
“bipartite”:
 $H \cap B = \emptyset$

Connecting cities

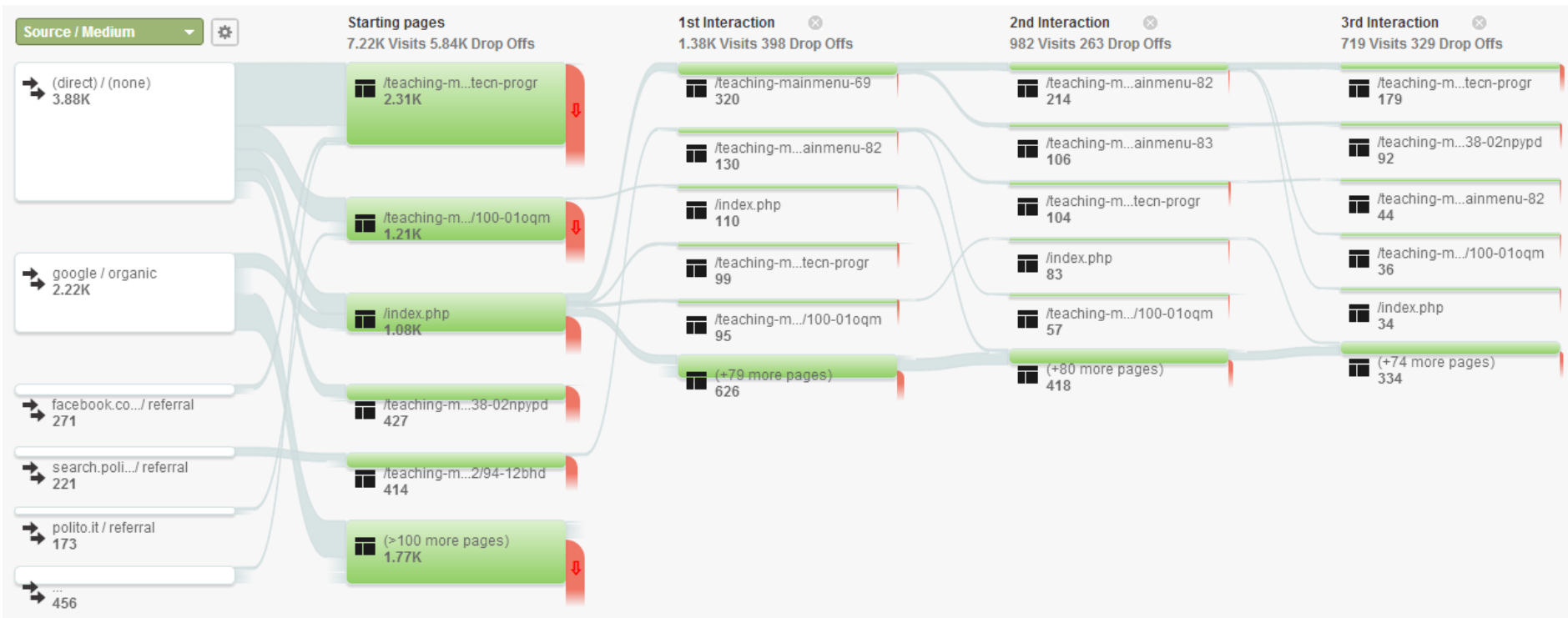
- ▶ We have a water reservoir
- ▶ We need to serve many cities
 - ▶ Directly or indirectly
- ▶ What is the most efficient set of inter-city water connections?

- ▶ Also for telephony, gas, electricity, ...

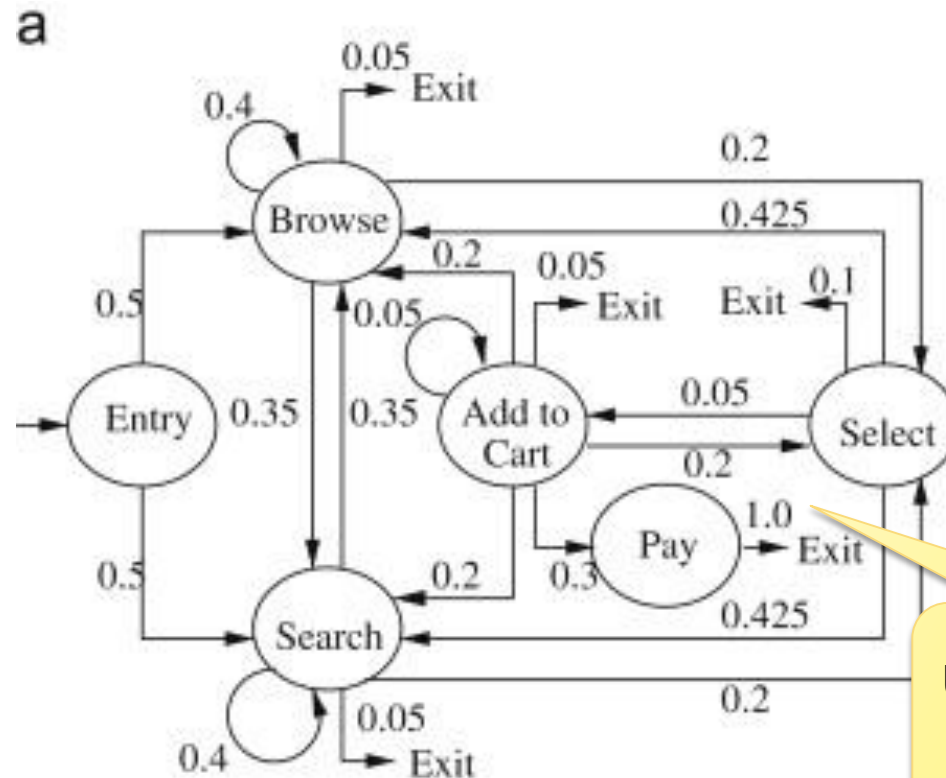
We are searching for the “minimum spanning tree”



Google Analytics (Visitors Flow)



Customer behavior



User actions encoded as frequencies

Street navigation



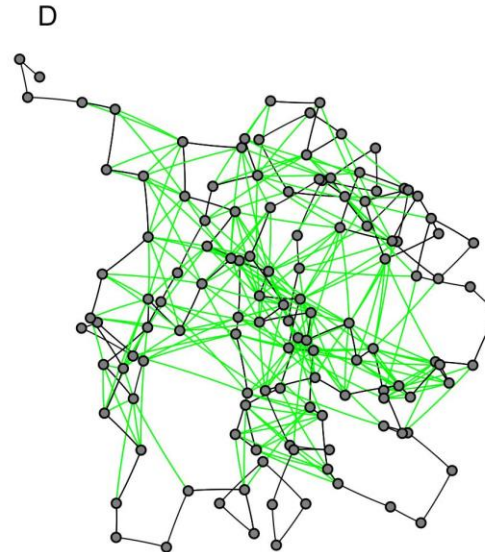
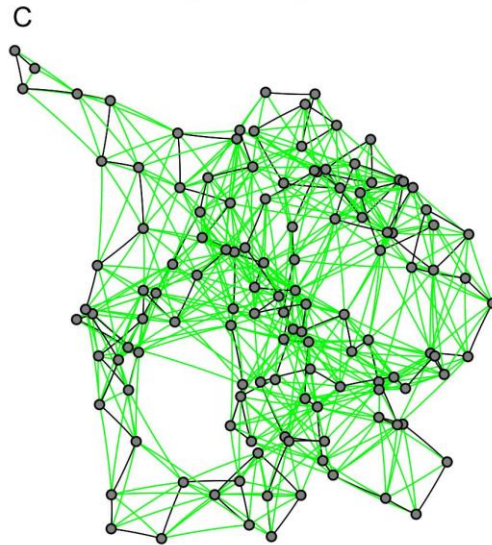
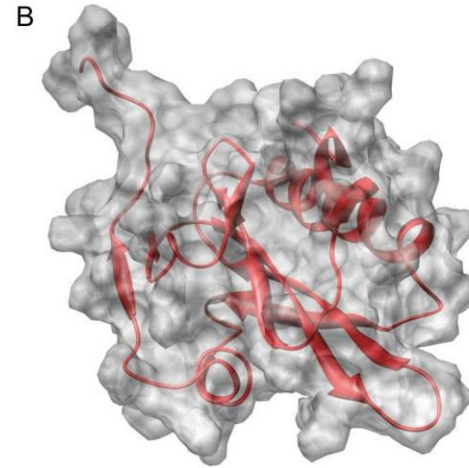
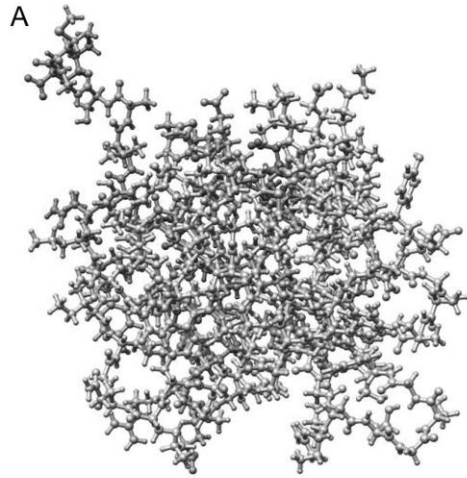
TSP: The traveling salesman problem

We must find a “Hamiltonian cycle”

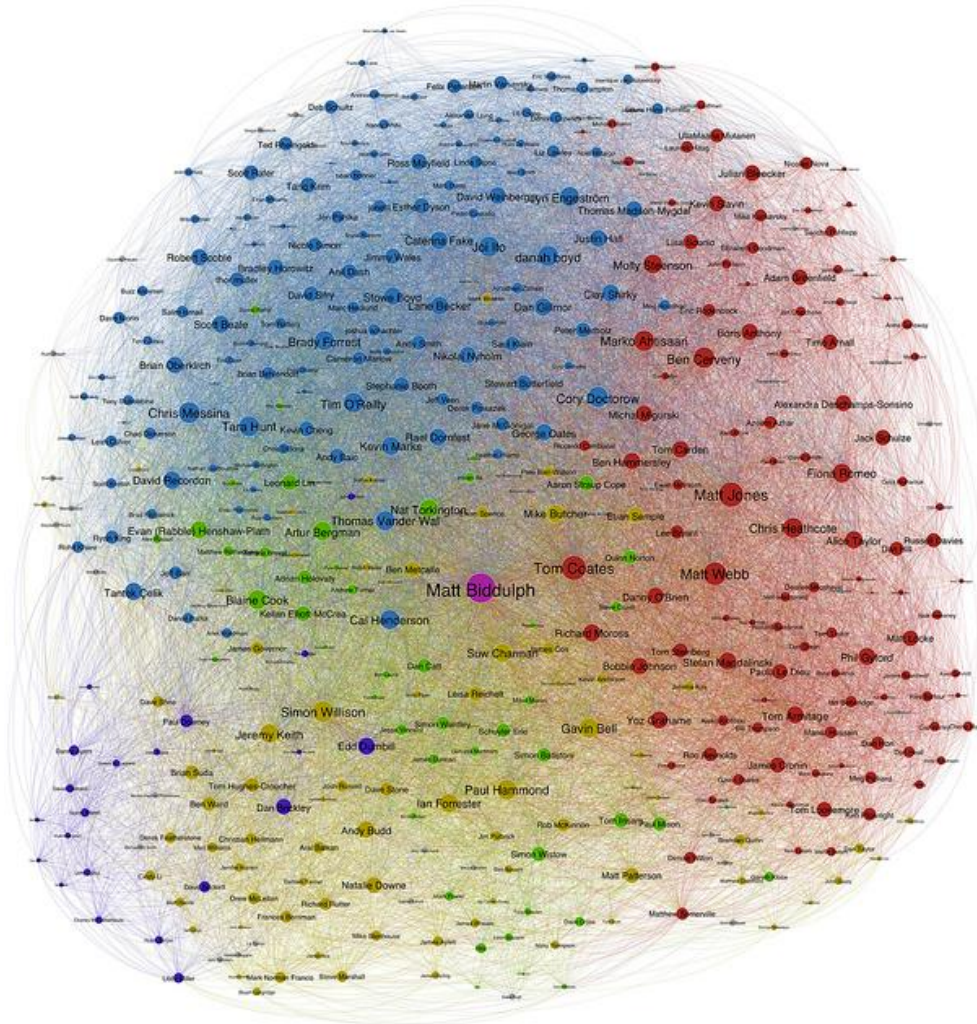
Train maps



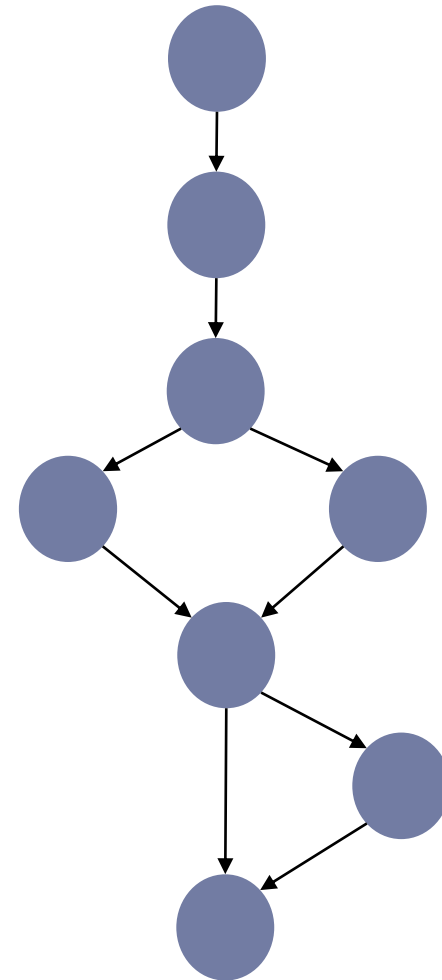
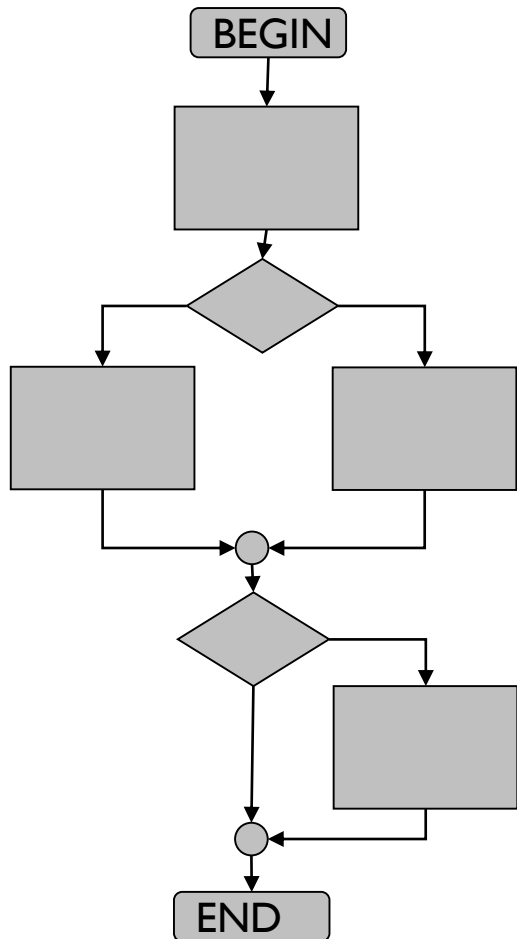
Chemistry (Protein folding)



Facebook friends



Flow chart



Representing graphs

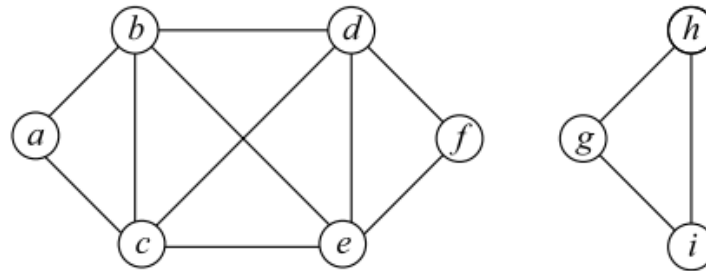
List structures

- ▶ **Adjacency list**
 - ▶ Each vertex has a list of which vertices it is adjacent to.
 - ▶ For undirected graphs, information is duplicated
- ▶ **Incidence list**
 - ▶ Each vertex has a list of 'edge' objects
 - ▶ Edges are represented by a pair (a tuple if directed) of vertices (that the edge connects) and possibly weight and other data.

Matrix structures

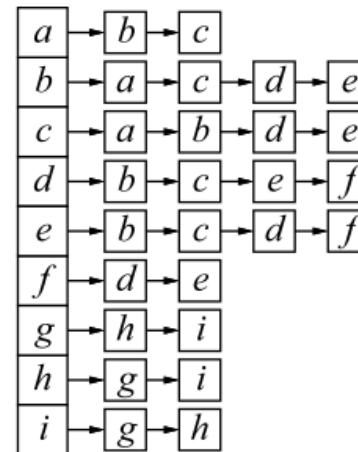
- ▶ **Adjacency matrix**
 - ▶ $A = |V| \times |V|$ matrix of Booleans or integers
 - ▶ If there is an edge from a vertex v to a vertex v' , then the element $A[v,v']$ is 1, otherwise 0.
- ▶ **Incidence matrix**
 - ▶ $IM = |V| \times |E|$ matrix of integers
 - ▶ $IM[v,e] = 1$ (incident), 0 (not incident)
 - ▶ For directed graphs, may be -1 (out) and +1 (in)

Example



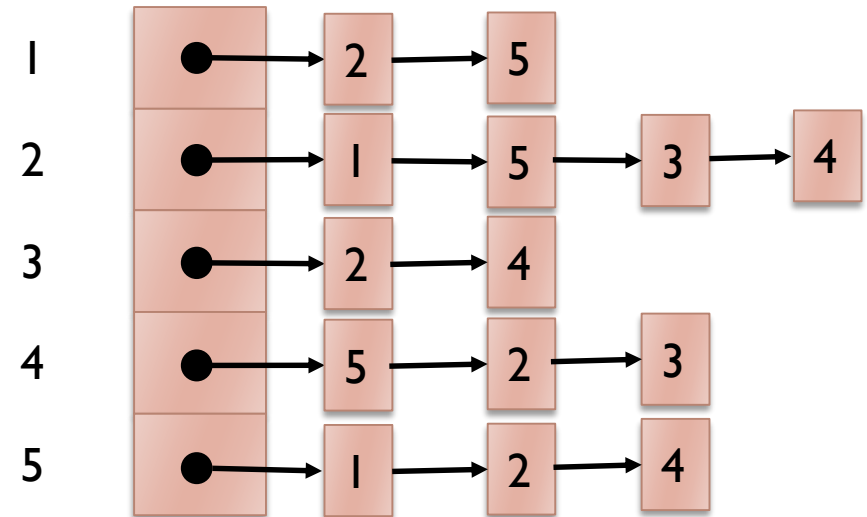
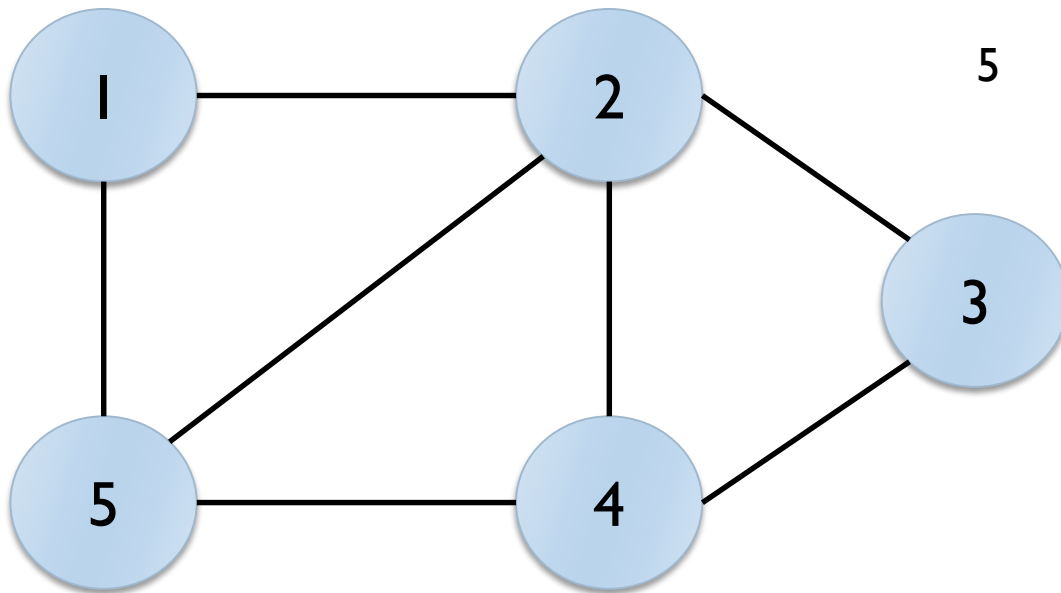
Adjacency
matrix

	<i>a</i>	<i>b</i>	<i>c</i>	<i>d</i>	<i>e</i>	<i>f</i>	<i>g</i>	<i>h</i>	<i>i</i>
<i>a</i>	0	1	1	0	0	0	0	0	0
<i>b</i>	1	0	1	1	1	0	0	0	0
<i>c</i>	1	1	0	1	1	0	0	0	0
<i>d</i>	0	1	1	0	1	1	0	0	0
<i>e</i>	0	1	1	1	0	1	0	0	0
<i>f</i>	0	0	0	1	1	0	0	0	0
<i>g</i>	0	0	0	0	0	0	0	1	0
<i>h</i>	0	0	0	0	0	0	1	0	1
<i>i</i>	0	0	0	0	0	0	1	1	0

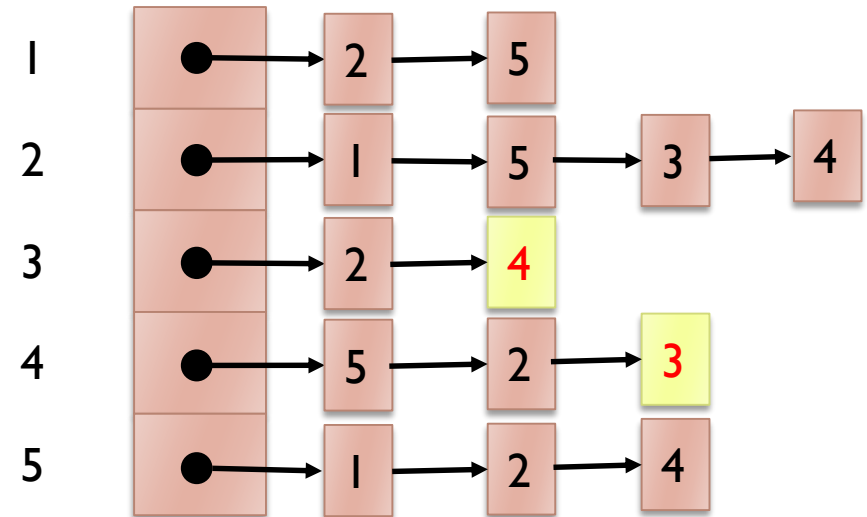
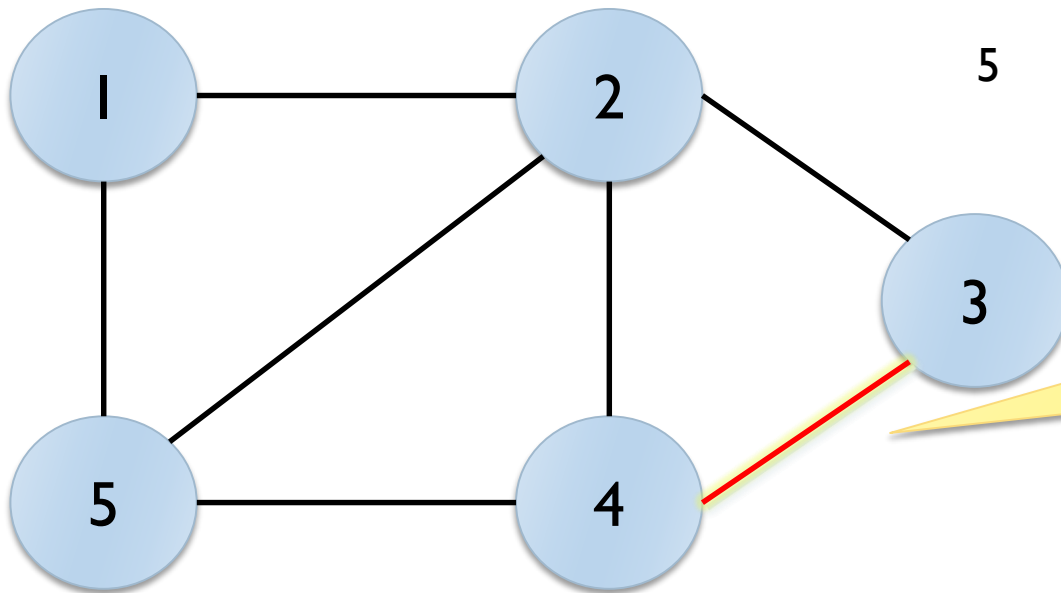


Adjacency
list

Adjacency list (undirected graph)

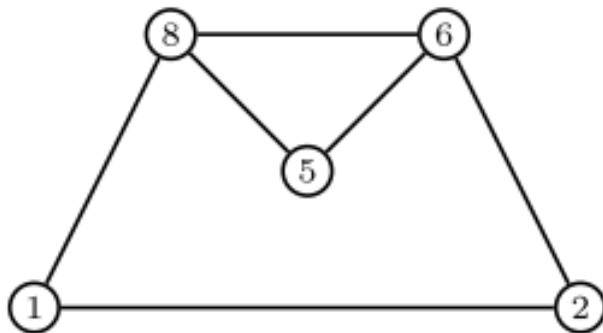


Adjacency list (undirected graph)



Undirected ==>
All edges are
represented twice

Adjacency list (un-connected graph)



$$L_1 = [2, 8]$$

$$L_2 = [1, 6]$$

$$L_3 = [4]$$

$$L_4 = [3]$$

$$L_5 = [6, 8]$$

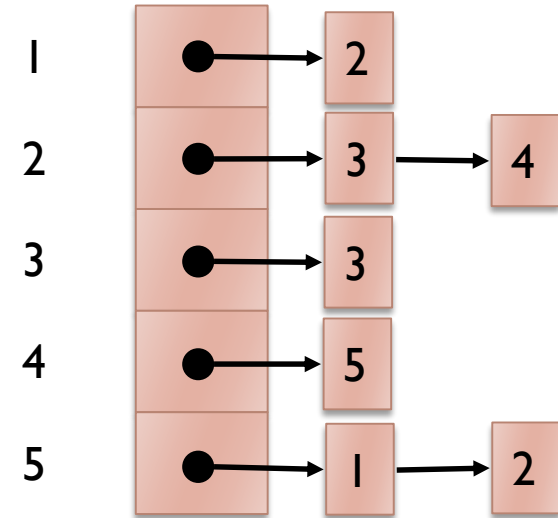
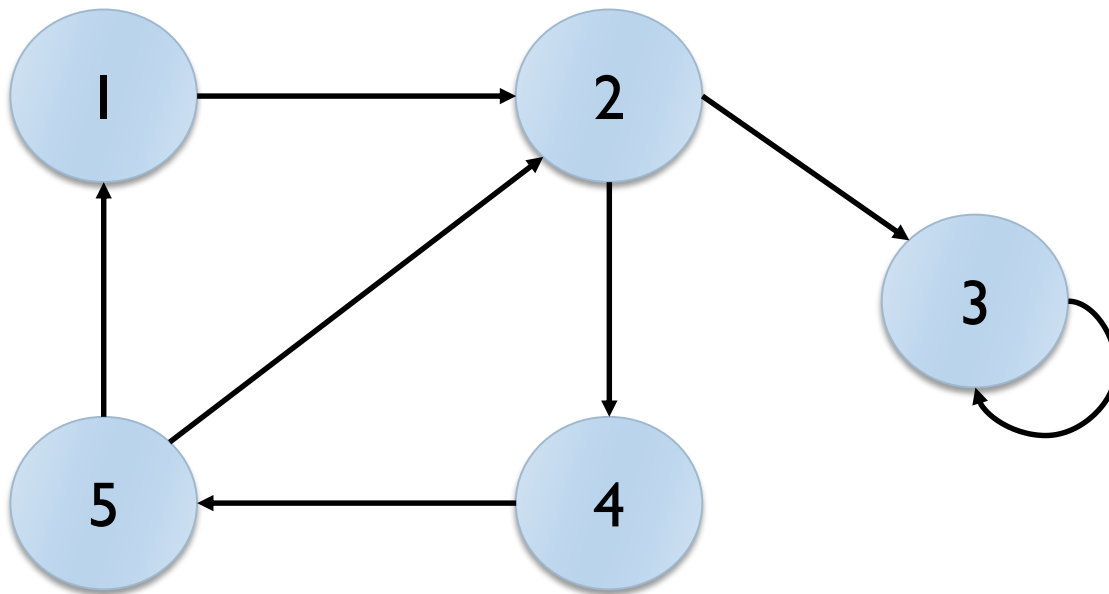
$$L_6 = [2, 5, 8]$$

$$L_7 = []$$

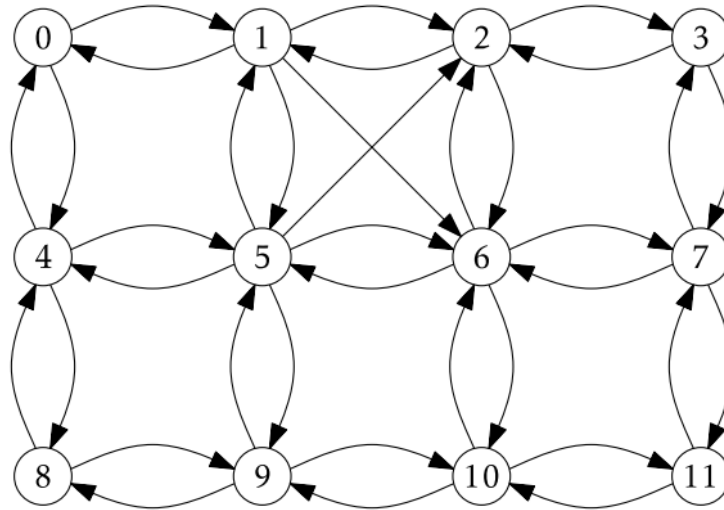
$$L_8 = [1, 5, 6]$$

Un-connected graph,
same rules

Adjacency list (directed graph)



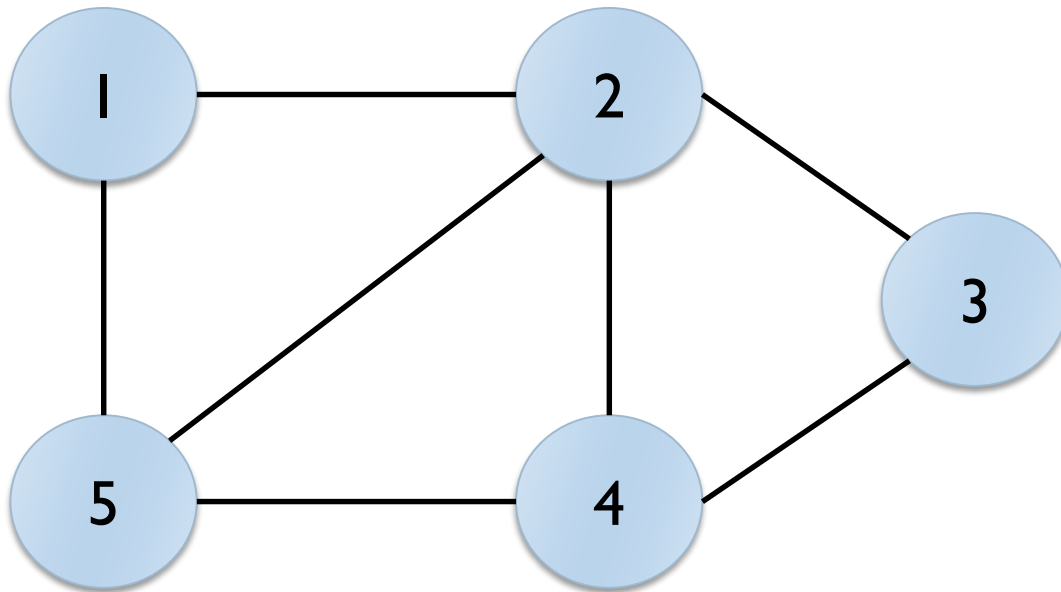
Adjacency list



0	1	2	3	4	5	6	7	8	9	10	11
1	0	1	2	0	1	5	6	4	8	9	10
4	2	3	7	5	2	2	3	9	5	6	7
	6	6		8	6	7	11		10	11	
	5				9	10					
					4						

Adjacency matrix (undirected graph)

Undirected =>
symmetric matrix

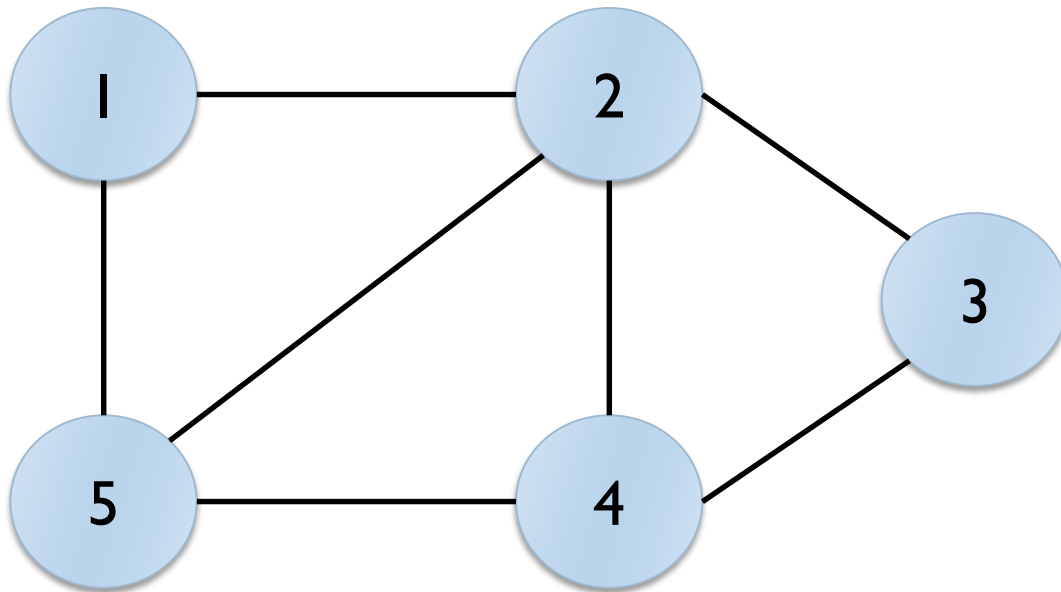


	1	2	3	4	5
1	0	1	0	0	1
2	1	0	1	1	1
3	0	1	0	1	0
4	0	1	1	0	1
5	1	1	0	1	0

No self-loops: zero
diagonal

Adjacency matrix (undirected graph)

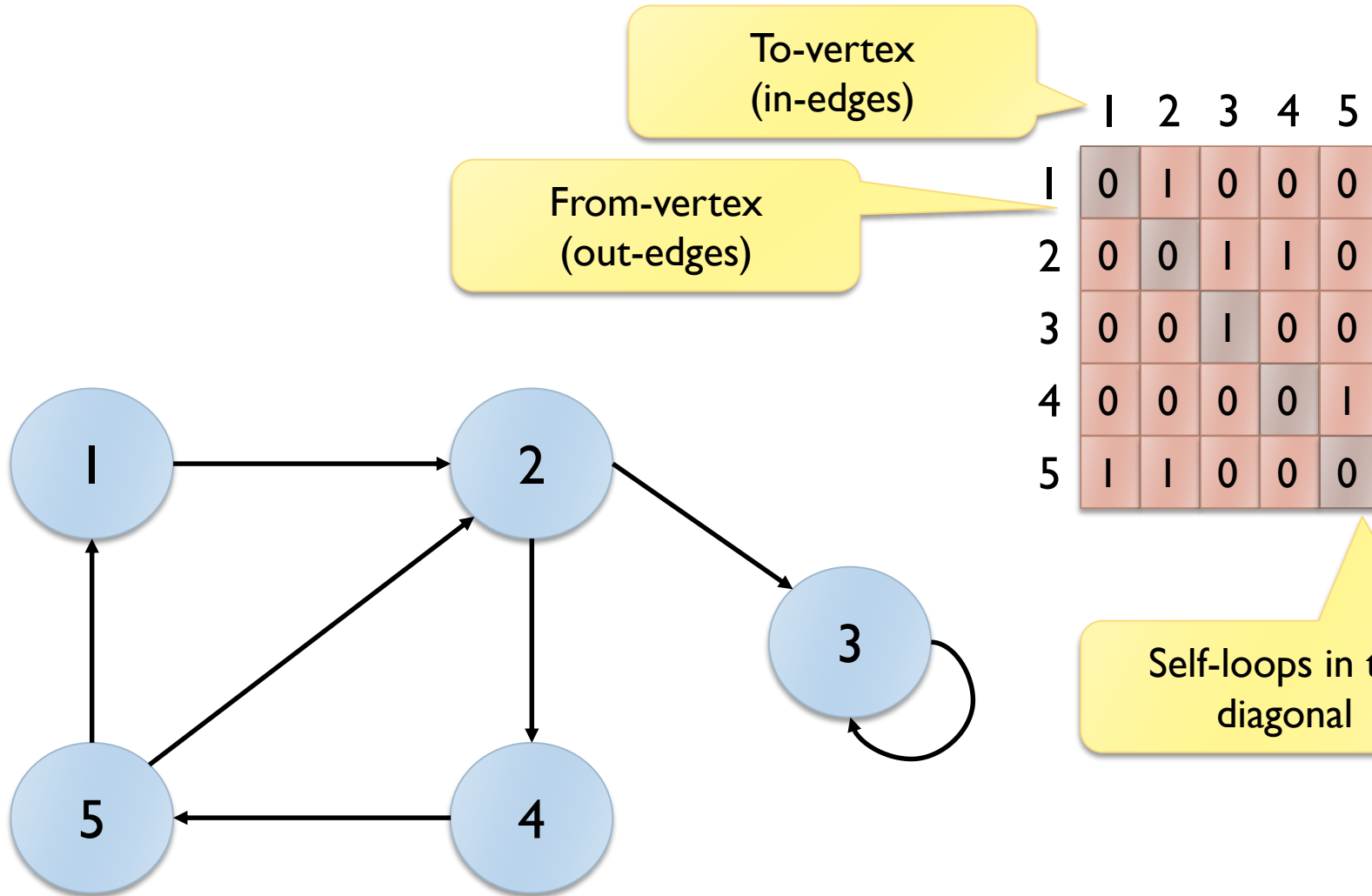
Undirected =>
symmetric matrix



	1	2	3	4	5
1		1	0	0	1
2			1	1	1
3				1	0
4					1
5					

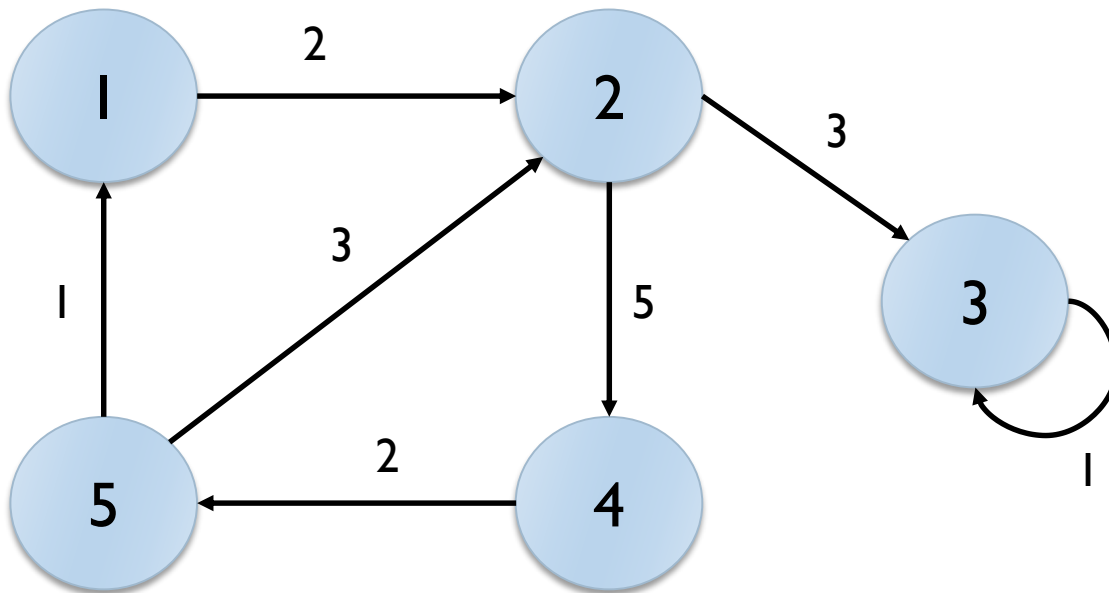
50% of memory can
be saved

Adjacency matrix (directed graph)



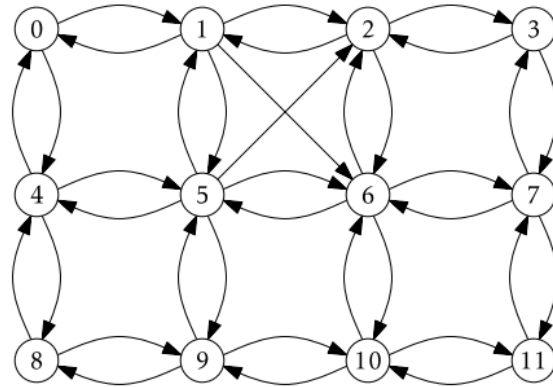
Adjacency matrix (weighted graph)

Values = edge weight



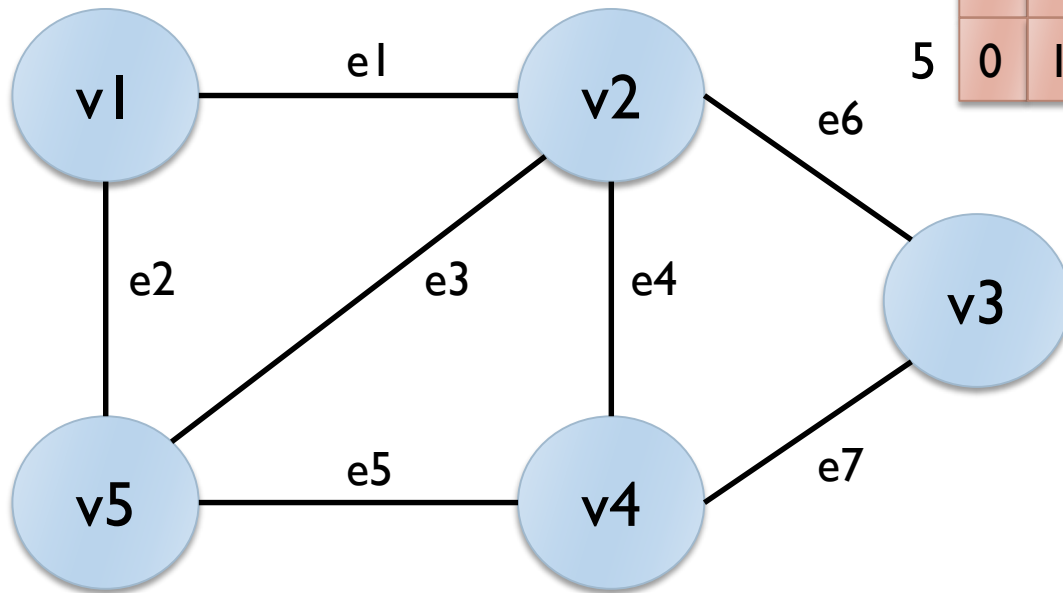
	1	2	3	4	5
1	0	2	0	0	0
2	0	0	3	5	0
3	0	0	1	0	0
4	0	0	0	0	2
5	1	3	0	0	0

Adjacency matrix



	0	1	2	3	4	5	6	7	8	9	10	11
0	0	1	0	0	1	0	0	0	0	0	0	0
1	1	0	1	0	0	1	1	0	0	0	0	0
2	1	0	0	1	0	0	1	0	0	0	0	0
3	0	0	1	0	0	0	0	1	0	0	0	0
4	1	0	0	0	0	1	0	0	1	0	0	0
5	0	1	1	0	1	0	1	0	0	1	0	0
6	0	0	1	0	0	1	0	1	0	0	1	0
7	0	0	0	1	0	0	1	0	0	0	0	1
8	0	0	0	0	1	0	0	0	0	1	0	0
9	0	0	0	0	0	1	0	0	1	0	1	0
10	0	0	0	0	0	0	1	0	0	1	0	1
11	0	0	0	0	0	0	0	1	0	0	1	0

Incidence matrix (undirected graph)



Vertices
v1...v5

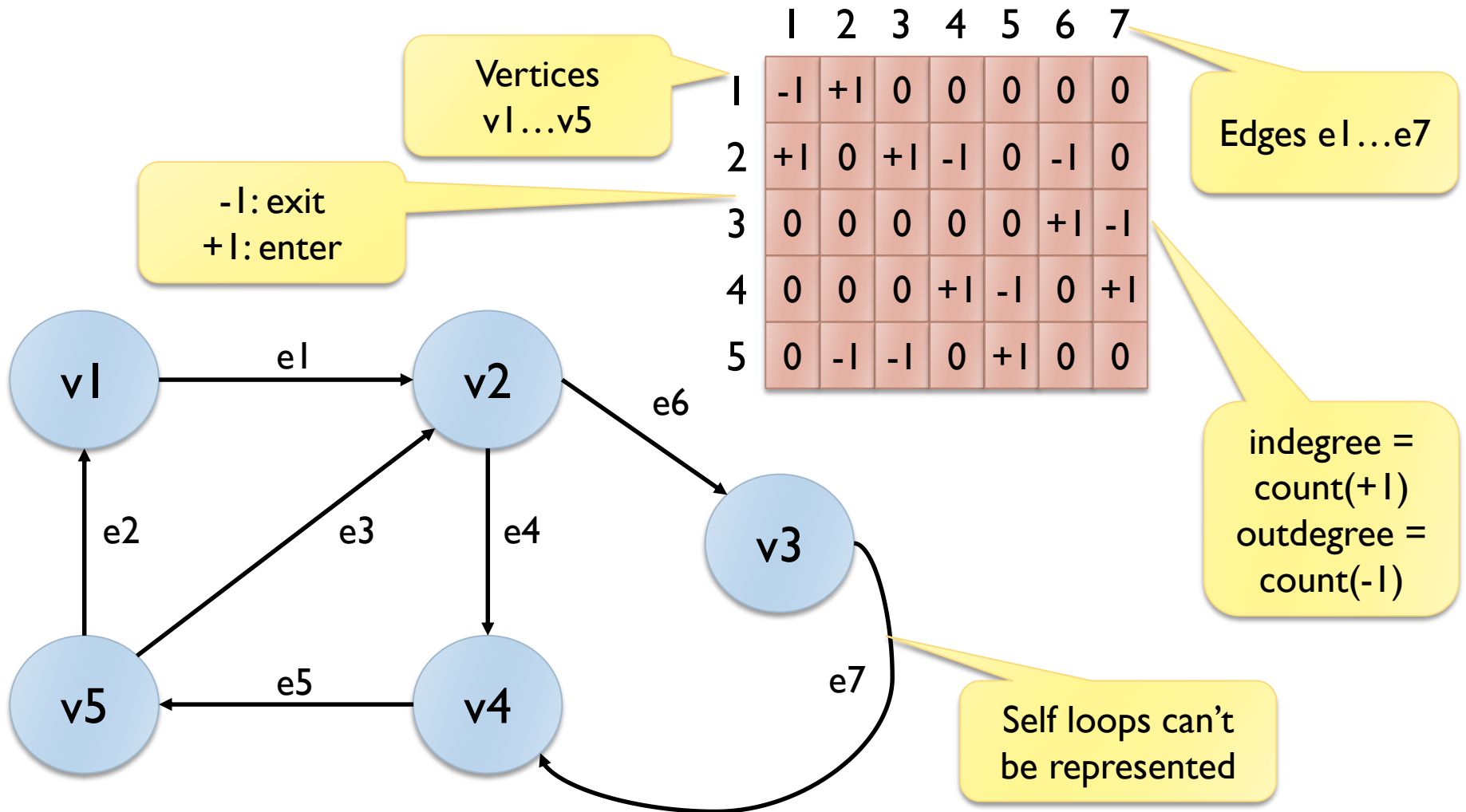
	1	2	3	4	5	6	7
1	1	1	0	0	0	0	0
2	1	0	1	1	0	1	0
3	0	0	0	0	0	1	1
4	0	0	0	1	1	0	1
5	0	1	1	0	1	0	0

Edges e1...e7

of "ones" in a row = vertex degree

Exactly 2 "ones" in every column

Incidence matrix (directed graph)



Complexity & trade-offs

	Adjacency List	Adjacency Matrix	Incidence Matrix
Space	$O(V + E)$	$O(V \times V)$	$O(V \times E)$
Space	For sparse graphs $ E \ll V ^2$	For dense graphs $ E \sim V ^2$	
Check edge	$O(1 + \text{deg}(v))$	$O(1)$	$O(E)$ if v, v' are known, or $O(1)$ if e is known
Find all adjacent	$O(1 + \text{deg}(v))$	$O(V)$	$O(V + E)$

Visit Algorithms

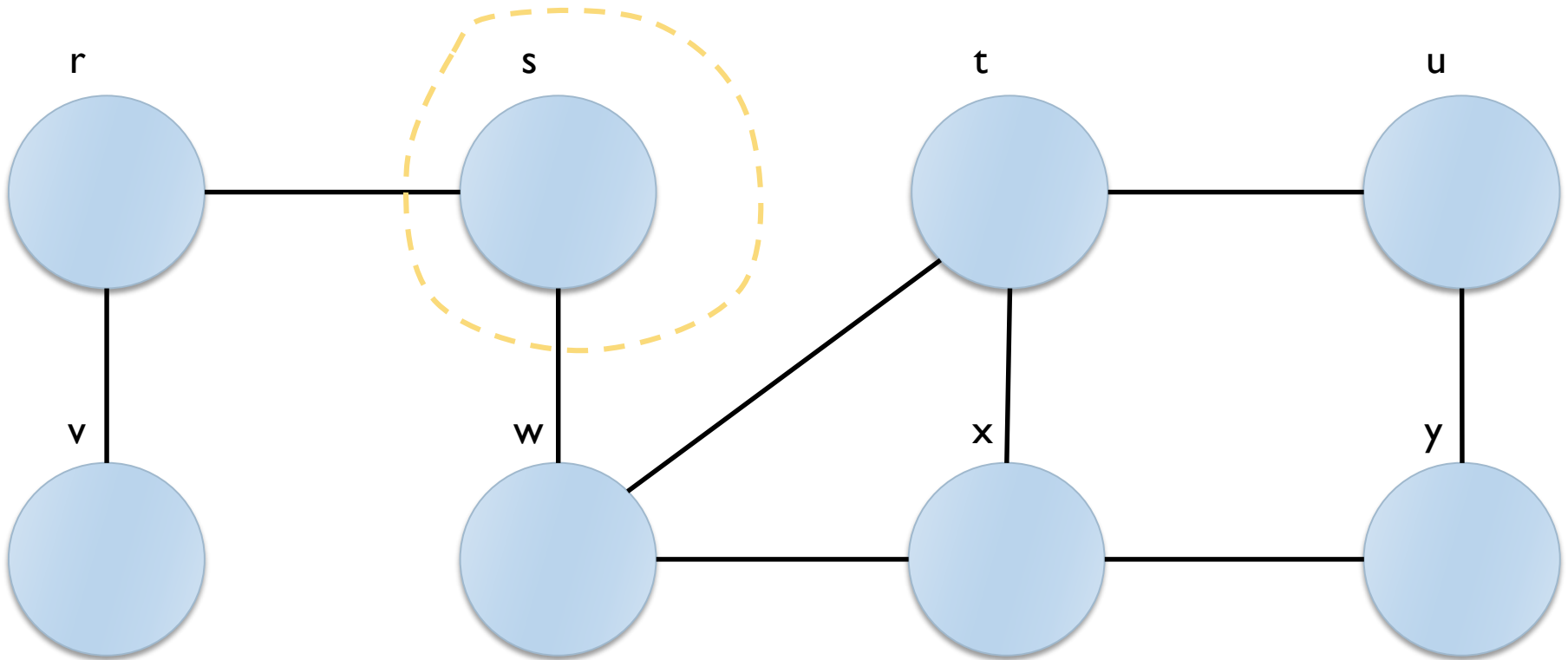
- ▶ **Visit =**
 - ▶ Systematic exploration of a graph
 - ▶ Starting from a ‘source’ vertex
 - ▶ Reaching all reachable vertices
- ▶ **Main strategies**
 - ▶ Breadth-first visit (“in ampiezza”)
 - ▶ Depth-first visit (“in profondità”)

Breadth-First Visit

- ▶ Also called Breadth-first search (BFV or BFS)
- ▶ All reachable vertices are visited “by levels”
 - ▶ L – level of the visit
 - ▶ S_L – set of vertices in level L
 - ▶ $L=0, S_0 = \{ v_{\text{source}} \}$
 - ▶ Repeat while S_L is not empty:
 - ▶ S_{L+1} = set of all vertices:
 - not visited yet, and
 - adjacent to at least one vertex in S_L
 - ▶ $L=L+1$

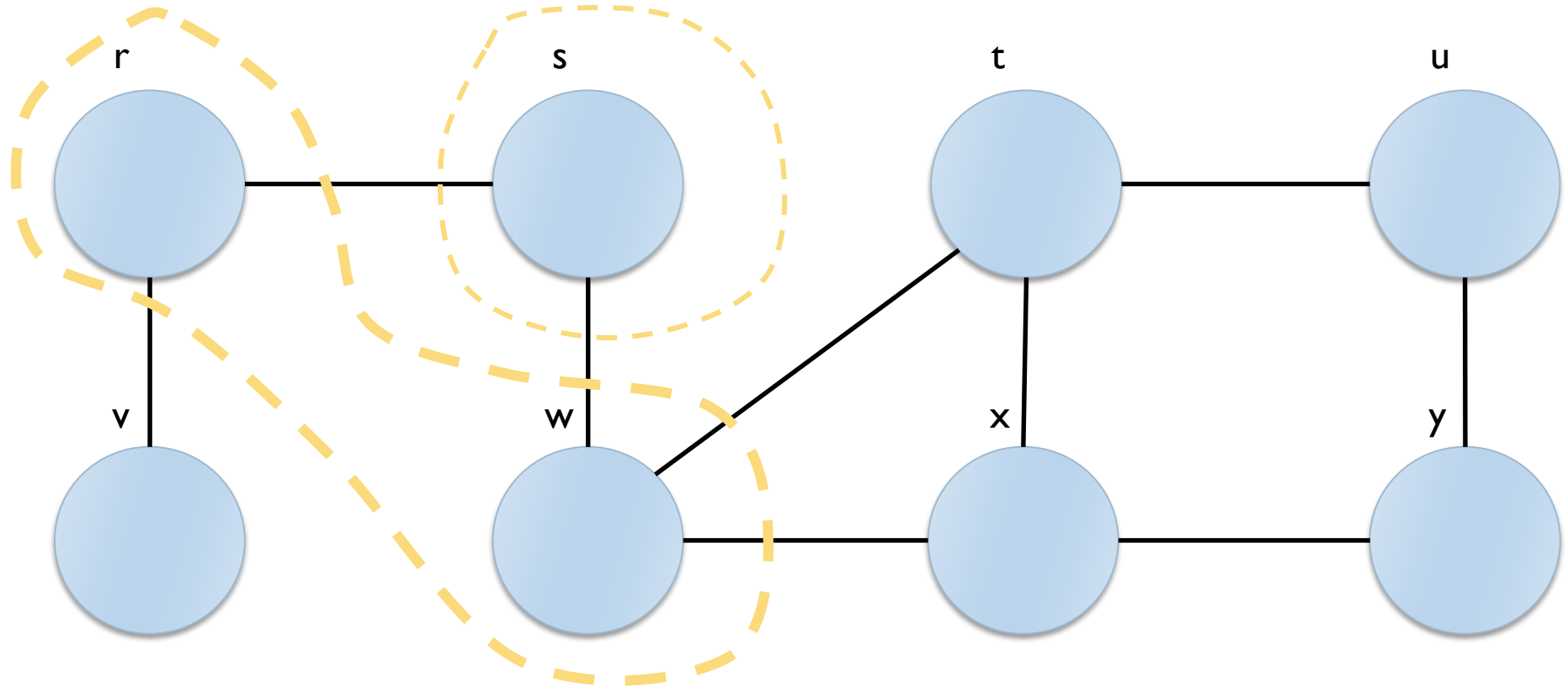
Example

Source = s
L = 0
 $S_0 = \{s\}$



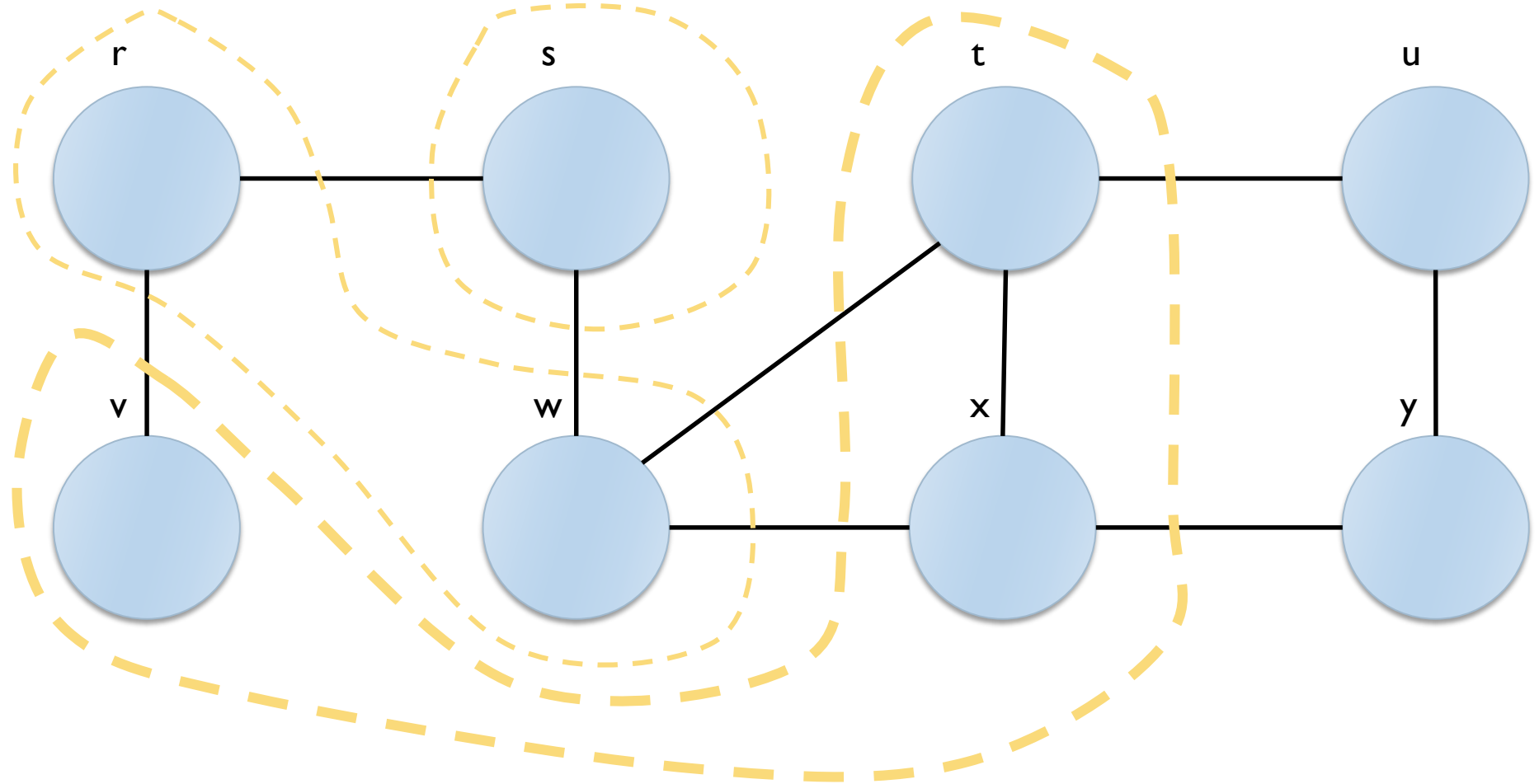
Example

$L = I$
 $S_0 = \{s\}$
 $S_1 = \{r, w\}$



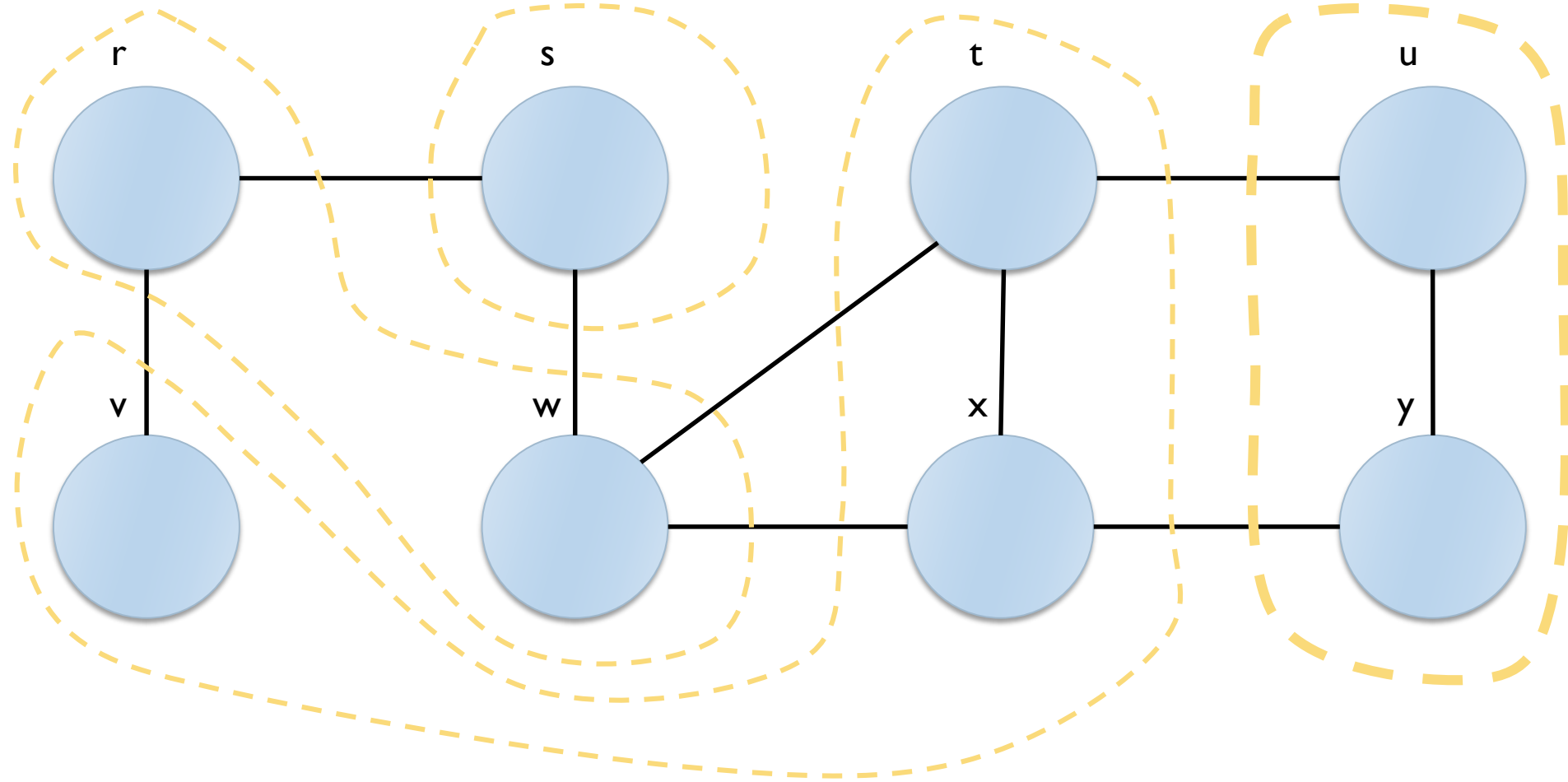
Example

$L = 2$
 $S_1 = \{r, w\}$
 $S_2 = \{v, t, x\}$



Example

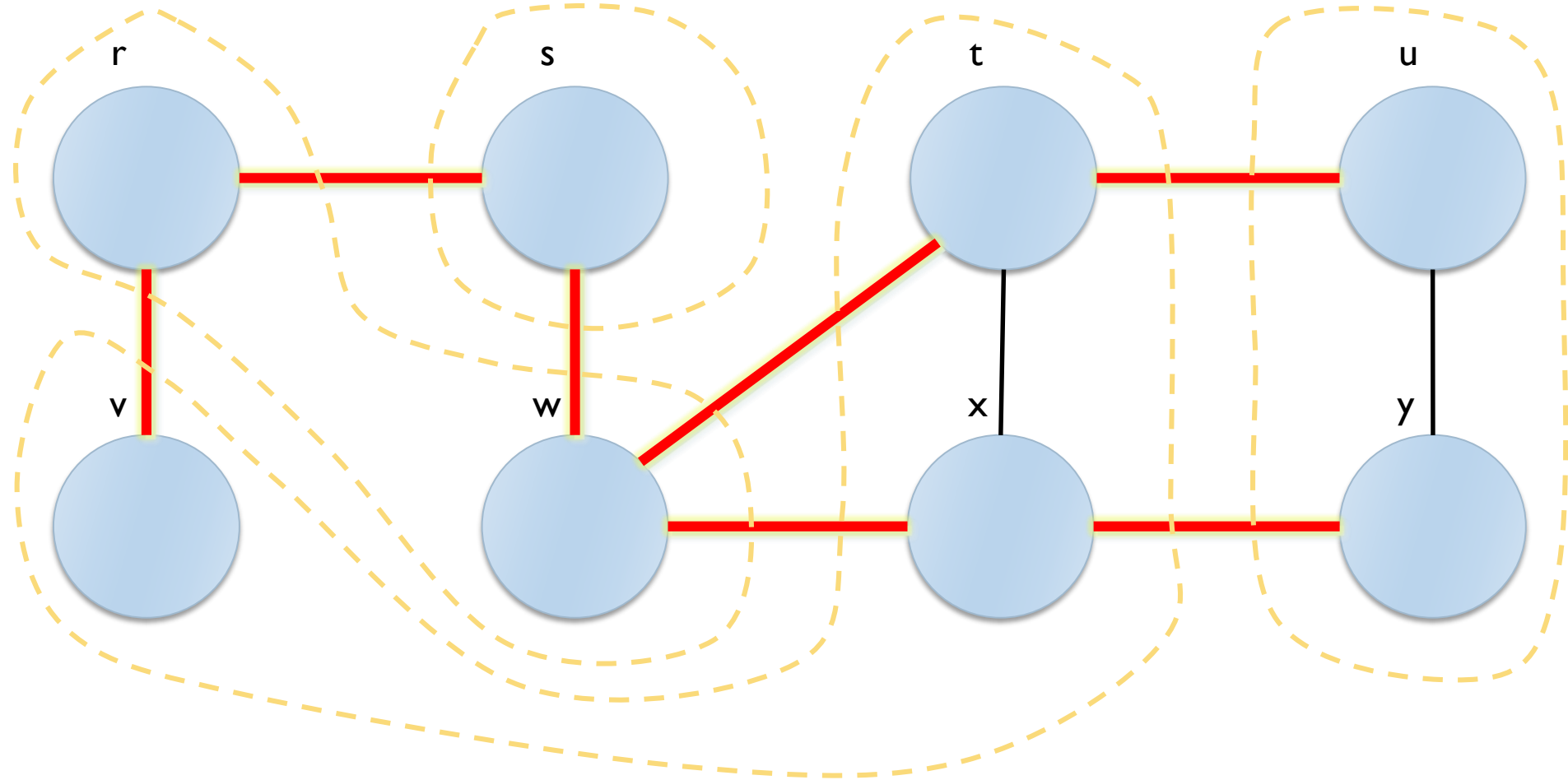
$L = 3$
 $S_2 = \{v, t, x\}$
 $S_3 = \{u, y\}$



BFS Tree

- ▶ The result of a BFV identifies a “visit tree” in the graph:
 - ▶ The tree root is the source vertex
 - ▶ Tree nodes are all graph vertices
 - ▶ (in the same connected component of the source)
 - ▶ Tree are a subset of graph edges
 - ▶ Those edges that have been used to “discover” new vertices.

BFS Tree



Minimum (shortest) paths

- ▶ Shortest path: the minimum number of edges on any path between two vertices
- ▶ The BFS procedure computes all minimum paths for all vertices, starting from the source vertex
- ▶ NB: unweighted graph : path length = number of edges

Depth First Visit

- ▶ Also called Depth-first search (DFV or DFS)
- ▶ Opposite approach to BFS
- ▶ At every step, visit one (yet unvisited) vertex, adjacent to the last visited one
- ▶ If no such vertex exist, go back one step to the previously visited vertex
- ▶ Lends itself to recursive implementation
 - ▶ Similar to tree visit procedures

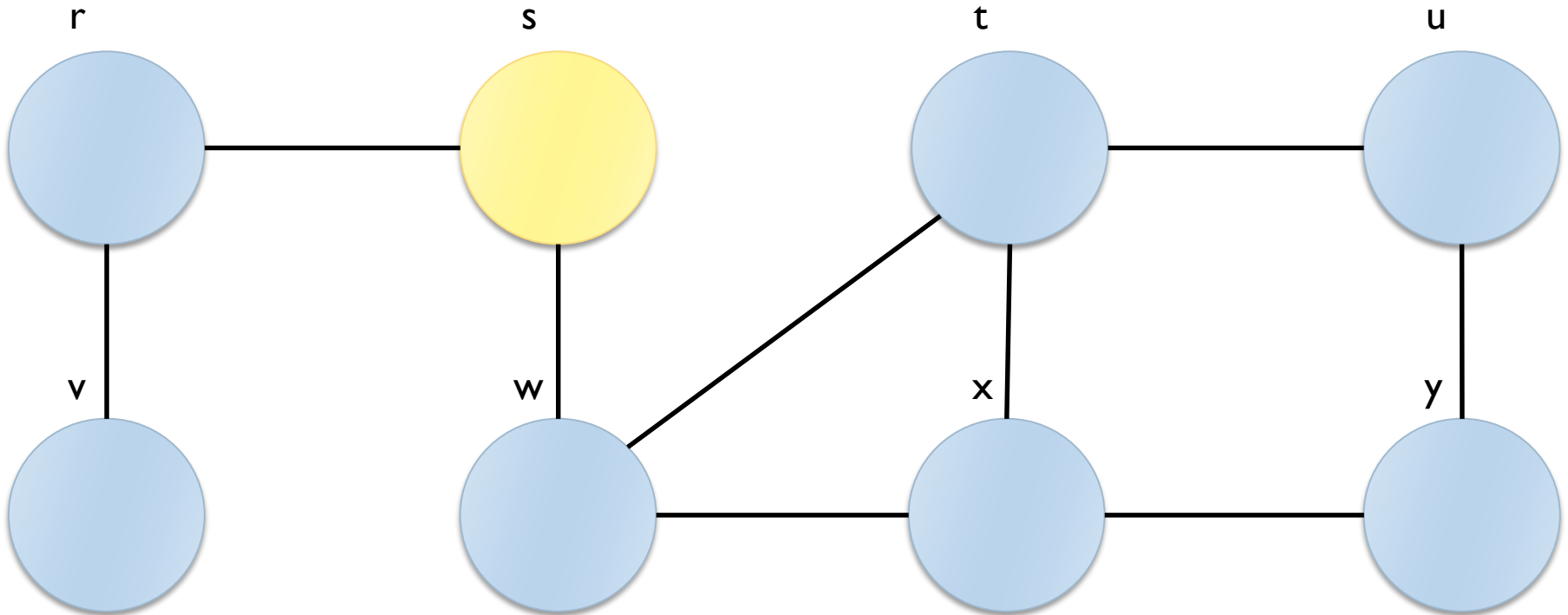
DFS Algorithm

- ▶ DFS(Vertex v)
 - ▶ For all ($w : \text{adjacent_to}(v)$)
 - ▶ If(not visited (w))
 - Visit (w)
 - DFS(w)

- ▶ Start with: DFS(source)

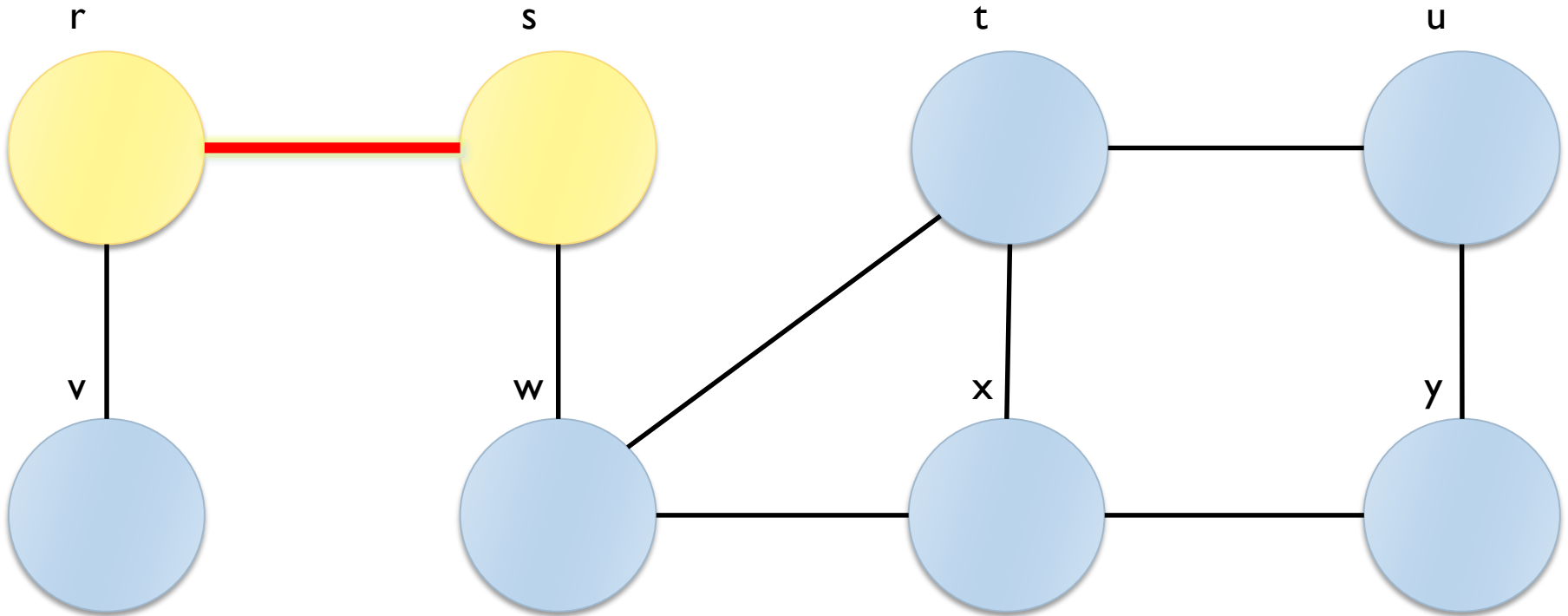
Example

Source = s



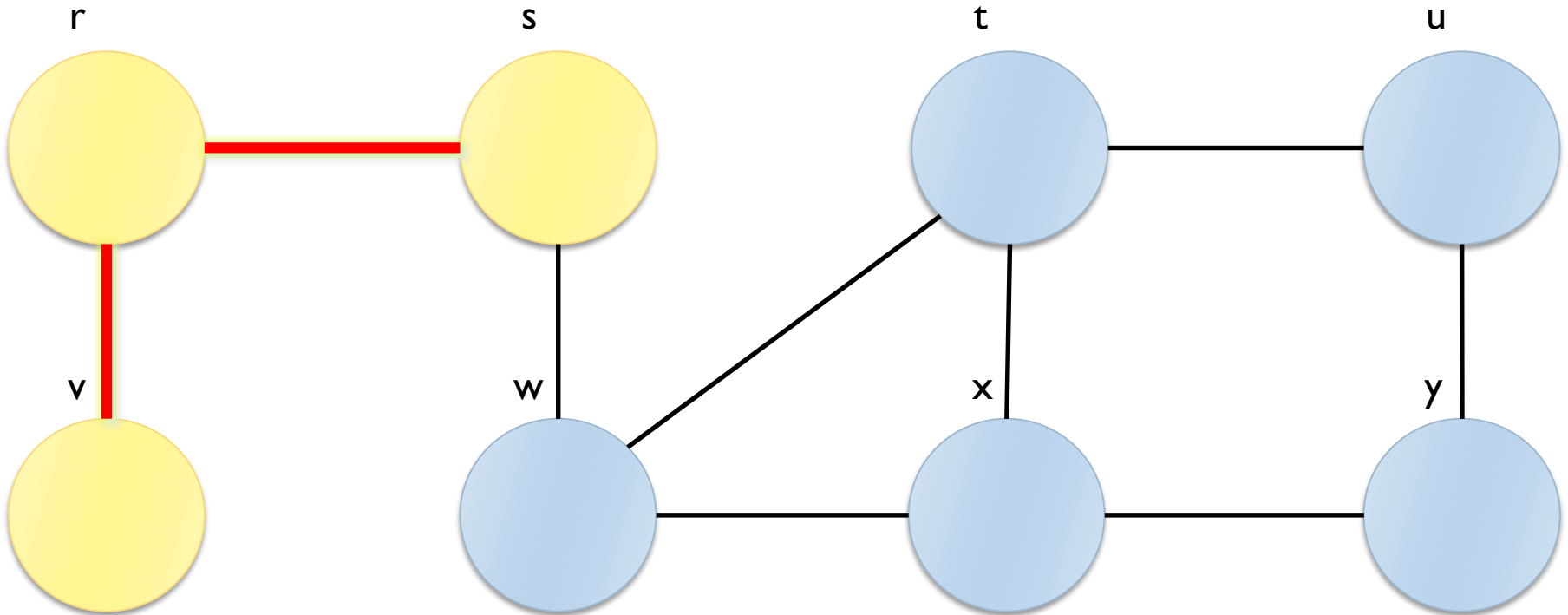
Example

Source = s
Visit r



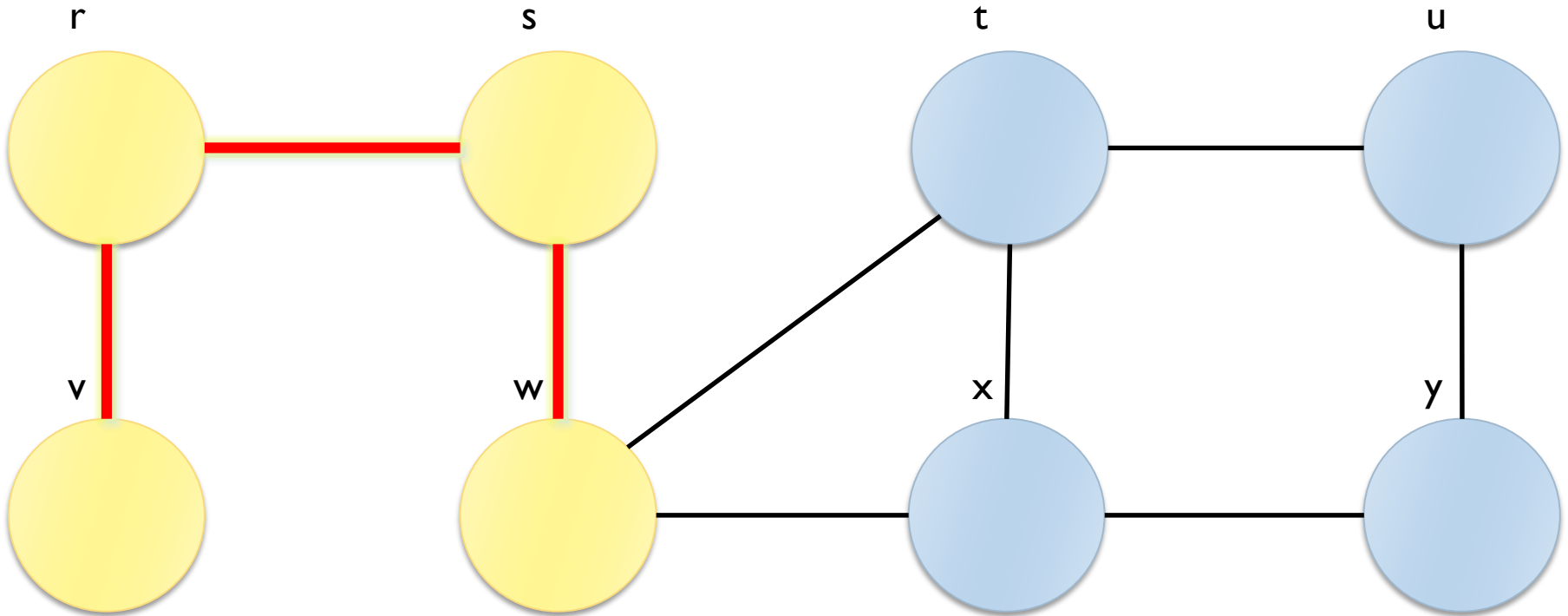
Example

Source = s
Visit r
Visit v



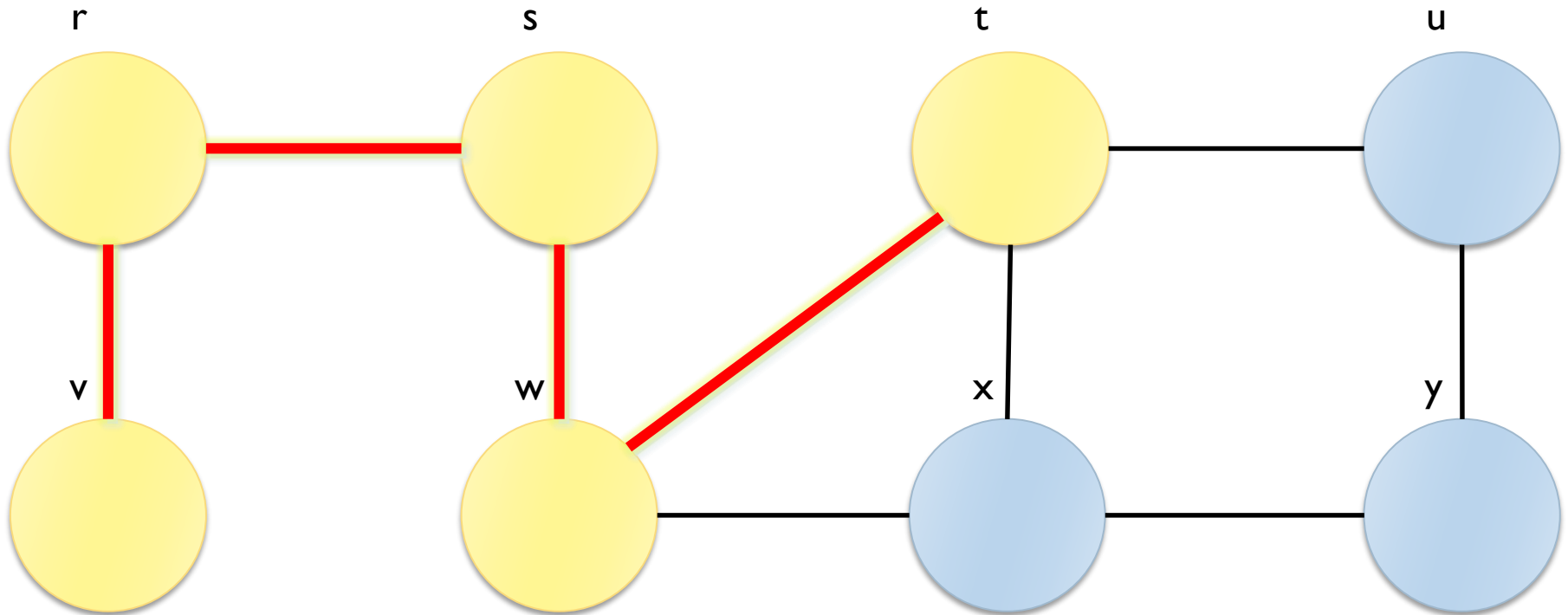
Example

Source = s
Back to r
Back to s
Visit w



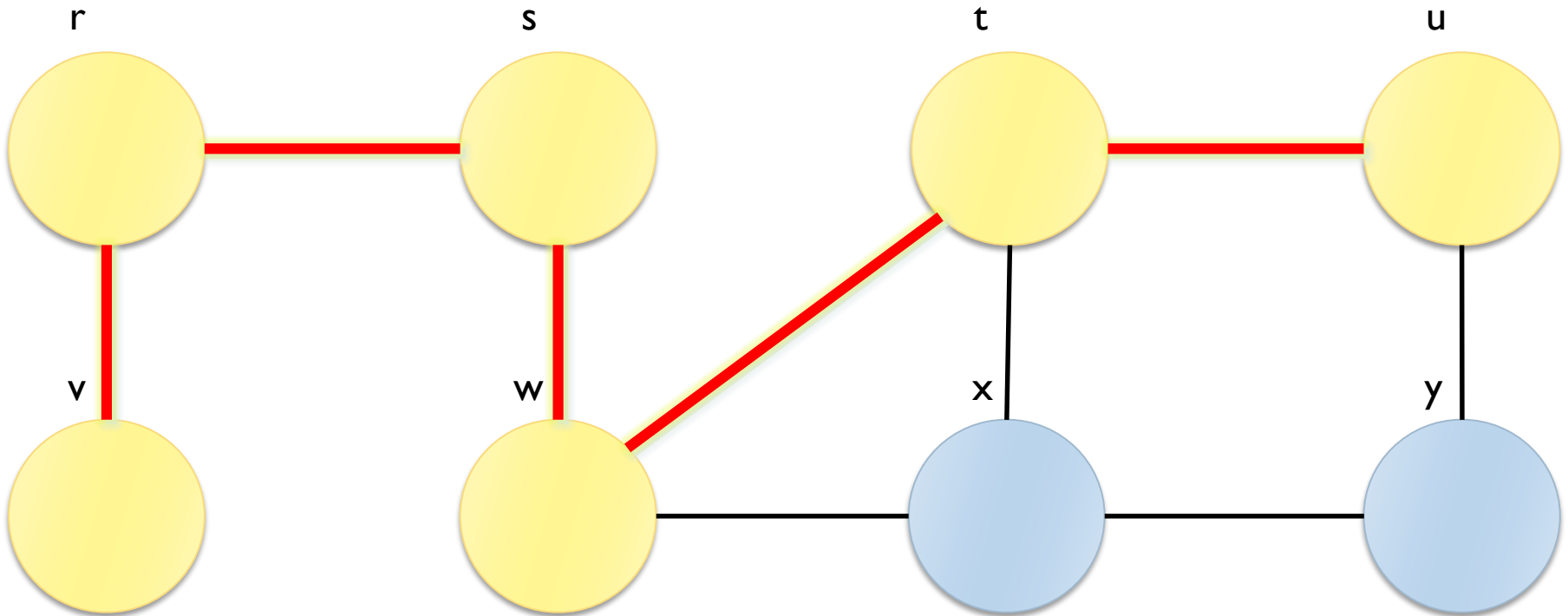
Example

Source = s
Visit w
Visit t



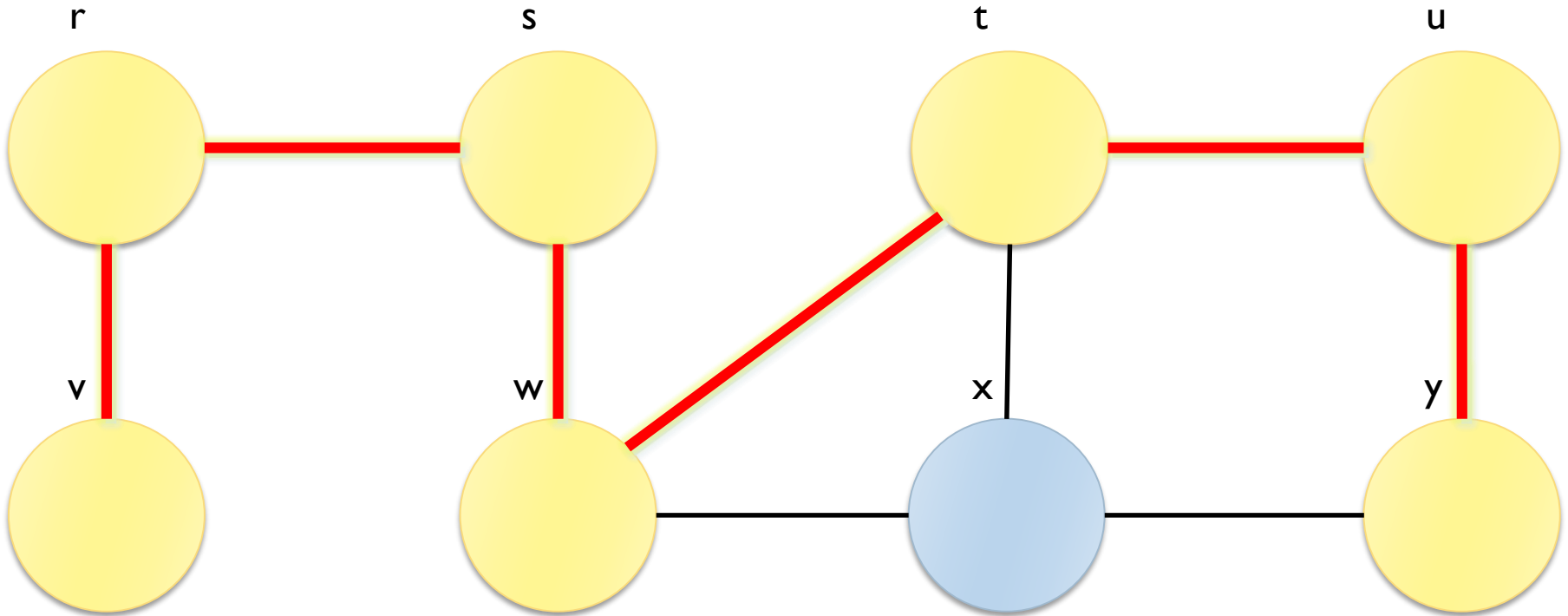
Example

Source = s
Visit w
Visit t
Visit u



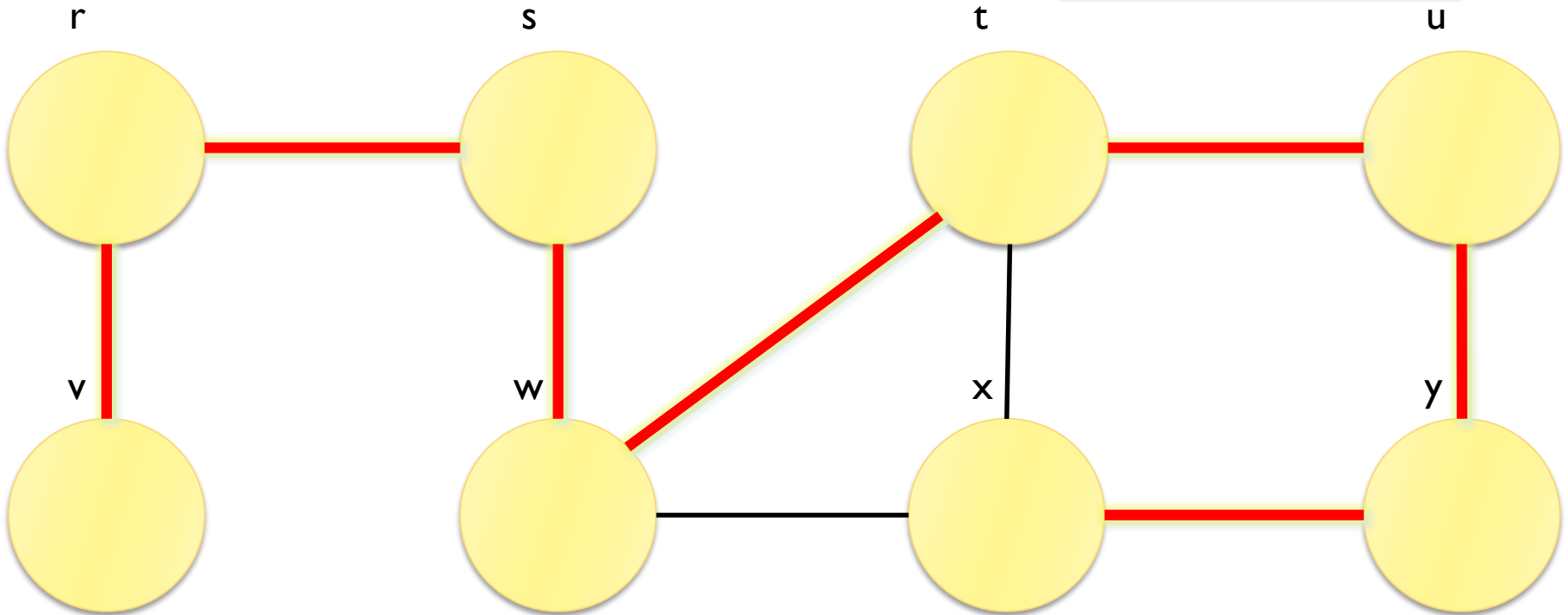
Example

Source = s
Visit w
Visit t
Visit u
Visit y

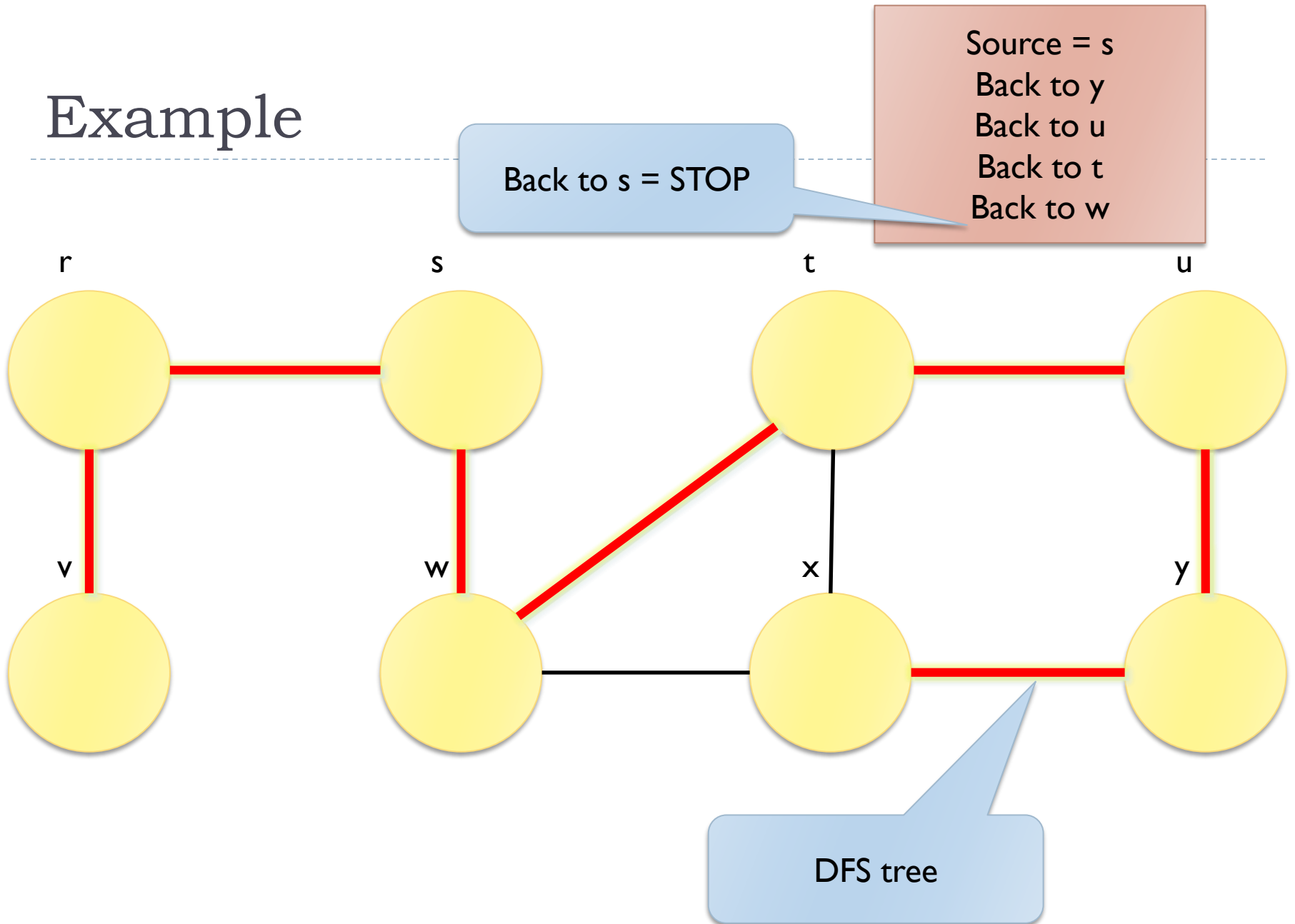


Example

Source = s
Visit w
Visit t
Visit u
Visit y
Visit x



Example

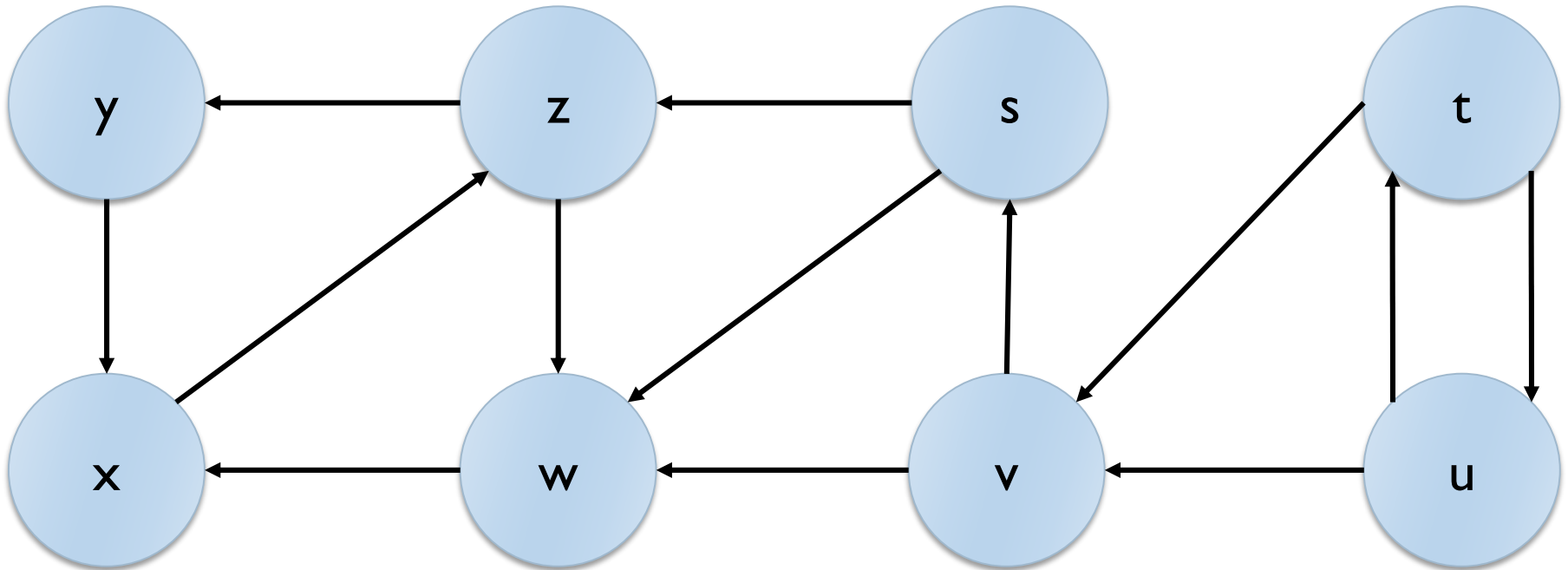


Edge classification

- ▶ In an directed graph, after a DFS visit, all edges fall in one of these 4 categories:
 - ▶ T: **Tree** edges (belonging to the DFS tree)
 - ▶ B: **Back** edges (not in T, and connect a vertex to one of its ancestors)
 - ▶ F: **Forward** edges (not in T and B, and connect a vertex to one of its descendants)
 - ▶ C: **Cross** edges (all remaining edges)

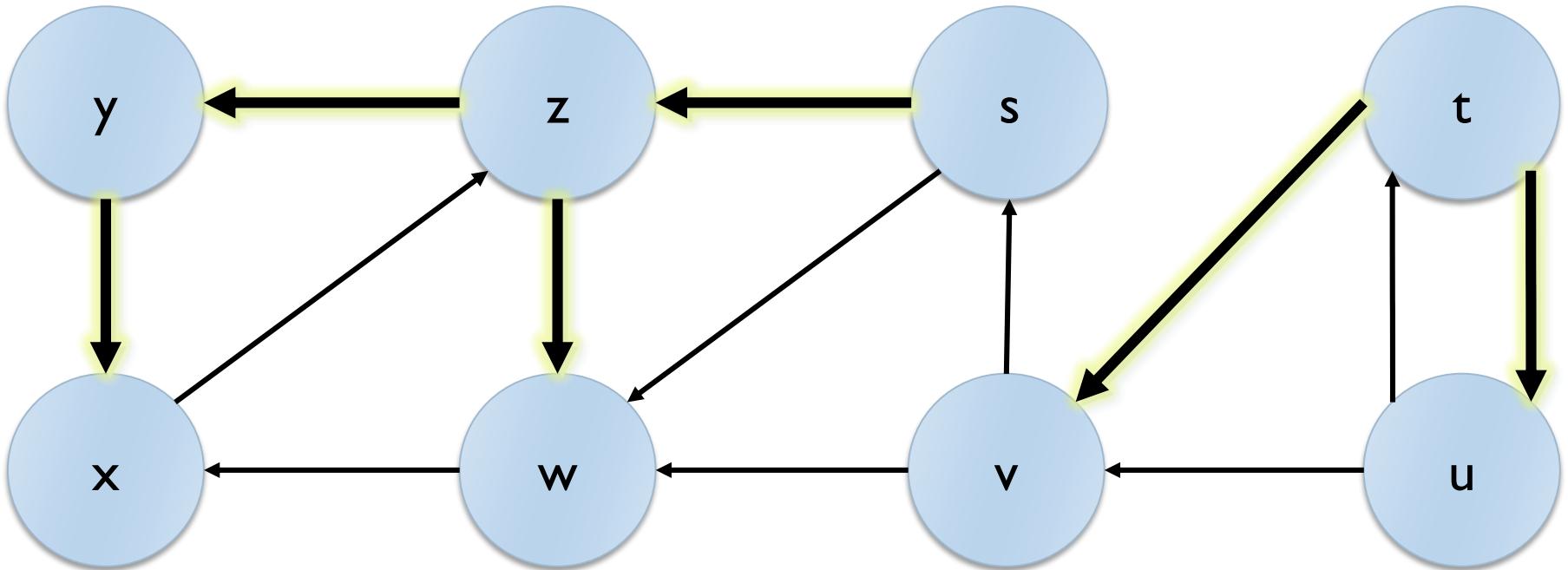
Example

Directed graph



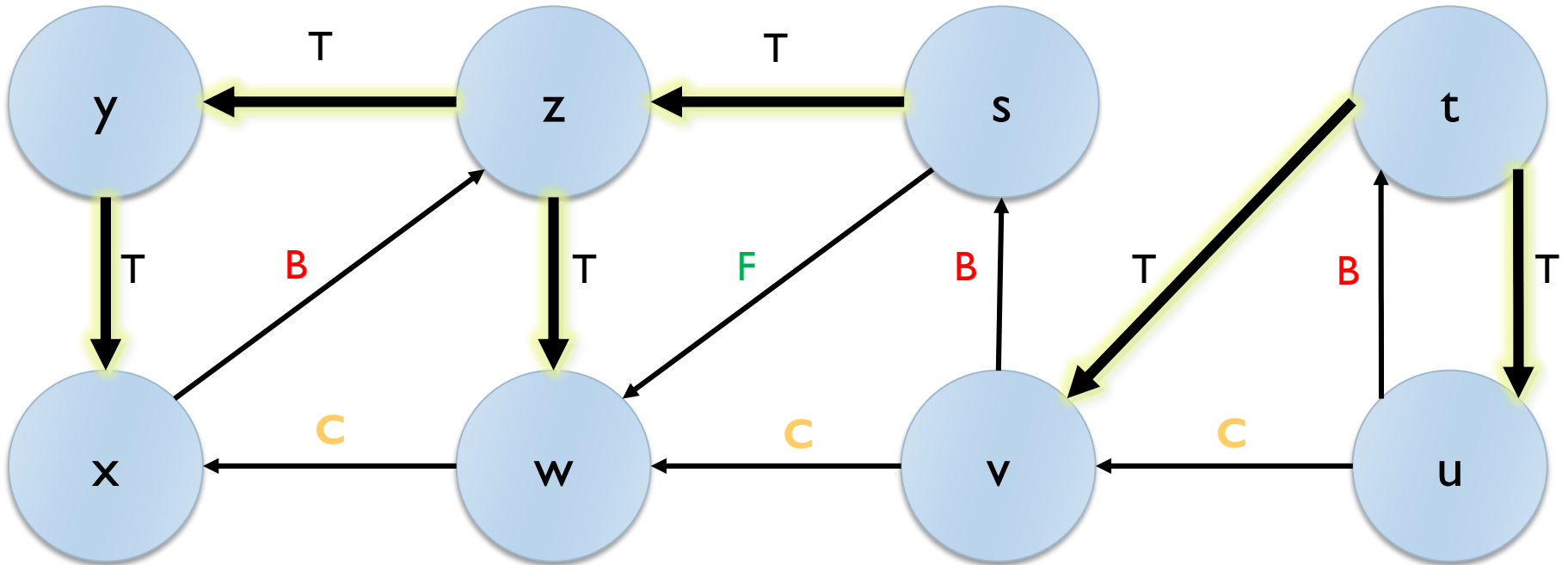
Example

DFS visit
(sources: s, t)



Example

Edge classification



Cycles

- ▶ Theorem:
- ▶ A directed graph is acyclic if and only if a depth-first visit does not produce any B edge

Complexity

- ▶ Visits have linear complexity in the graph size
 - ▶ BFS : $O(V+E)$
 - ▶ DFS : $\Theta(V+E)$
- ▶ N.B. for dense graphs, $E = O(V^2)$

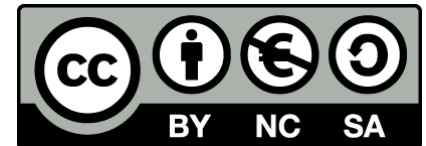
Resources






- ▶ Maths Encyclopedia: <http://mathworld.wolfram.com/>
- ▶ Basic Graph Theory with Applications to Economics
<http://www.isid.ac.in/~dmishra/mpdoc/lecgraph.pdf>
- ▶ Application of Graph Theory in real world
<http://prezi.com/tsehIwvpves-/application-of-graph-theory-in-real-world/>

Resources

- ▶ Open Data Structures (in Java), Pat Morin, <http://opendatastructures.org/>
- ▶ Algorithms Course Materials, Jeff Erickson, <http://www.cs.uiuc.edu/~jeffe/teaching/algorithms/>
- ▶ Graphbook - A book on algorithmic graph theory, David Joyner, Minh Van Nguyen, and David Phillips, <https://code.google.com/p/graphbook/>

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